

What is Monte Carlo Modeling*?

Monte Carlo Modeling is a statistical method used here to simulate radiative transfer by simulating photon (or more exactly light rays/beams) interaction with a medium.

MC models can be built such that increasing complexity can be added as the model develops.

*based partially on a ppt file found at: www.ece.utexas.edu/bell/MonteCarlo.ppt

Program

Some steps and concepts needed to implement a Monte Carlo model of photon propagation in a medium:

- Random Number Generation
- Attenuation of beam in the medium
- Scattering of Photons
- Variable weight photon
- Index Mismatch of Boundary Layers
- Grid Structure
- Detector
- Inverse MC (from detector → source)

Basic concepts:

The "fundamental principle": we can map any probability distribution to a uniform distribution from 0 to 1:

$$\xi = \int_{-\infty}^{x_0} p(x) dx = P(x_0)$$

Example: the probability of a photon travel to a distance l (or an optical depth $\tau=cl$) without an interaction is $\exp(-\tau)$.

$$\xi = \int_{-\infty}^l \exp(-\tau) d\tau = 1 - \exp(-\tau)$$

$$\rightarrow \tau = -\log(1 - \xi) = -\log(\xi)$$

For a uniform medium: $\rightarrow l = -\log(\xi) / c$

Random Number Generation

- The first step in building a Monte Carlo model is to have a method to create random numbers.
- In Matlab the function 'rand.m' generates a uniform distribution of random numbers (r.n.) in (0,1). ← see: [gen_rand.m](#)
- Random number generators produce 'pseudo' random numbers.

Essential Properties of a Random Number Generator*

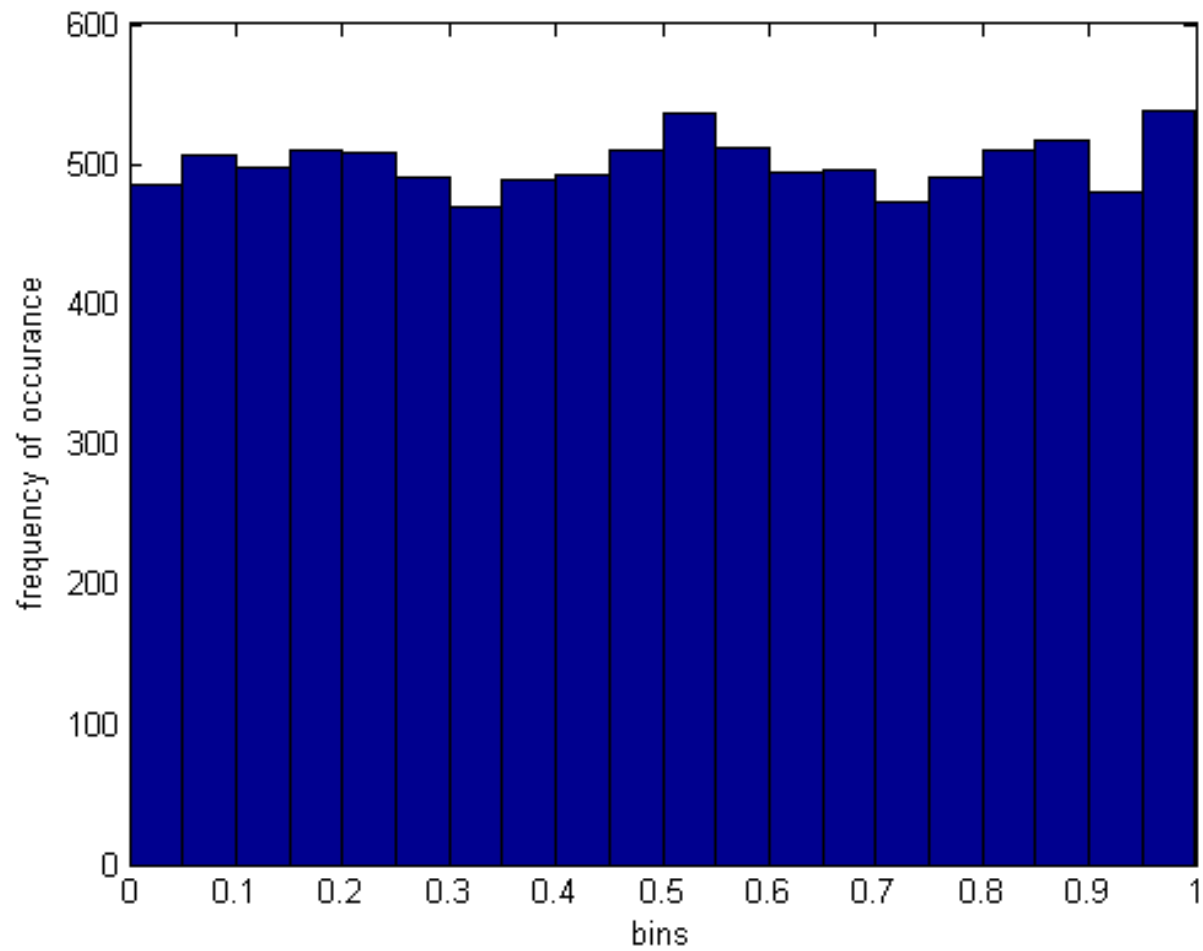
- **Repeatability** -- the same sequence should be produced with the same initial values (or *seed*). This is vital for debugging.
- **Randomness** -- should produce independent uniformly distributed random variables that pass all statistical tests for randomness.
- **Long period** -- a pseudo-random number sequence uses finite precision arithmetic, so the sequence must repeat itself with a finite period. This period should be much longer than the amount of random numbers needed for the simulation.
- **Insensitive to seeds** -- period and randomness properties should not depend on the initial seeds.

*http://www.npac.syr.edu/users/paulc/lectures/montecarlo/p_montecarlo.html

Concepts

- Test if r.n. is "uniformly", i.e., equally distributed
- Generate 10,000 r.n. and divide the (0,1) axis into 20 equal intervals.
- Observe the frequency of occurrence of r.n. in each interval. The ideal mean value is 500.
- Observe the standard deviation. The standard deviation should be less than 36.

Results

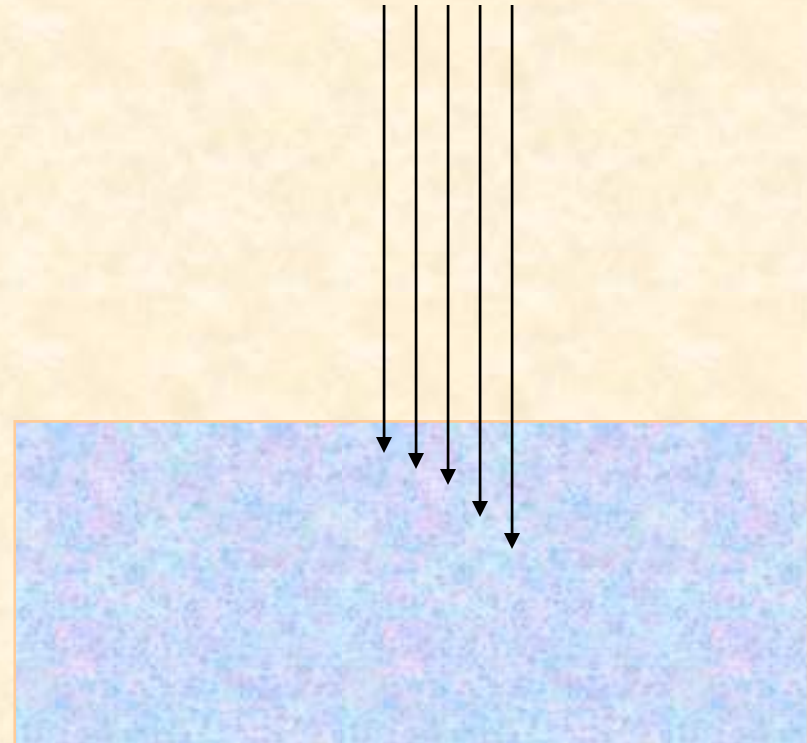


Std=18.05

Attenuation of a Collimated Beam

- The goal of this step is to figure out how photons are attenuated in the medium.
- Attenuation coefficient is c with units m^{-1} .
- Attenuation obeys Beer-Lambert-Bouguer's Law:

$L = L_0 e^{-cz}$, where z is the depth within the medium.

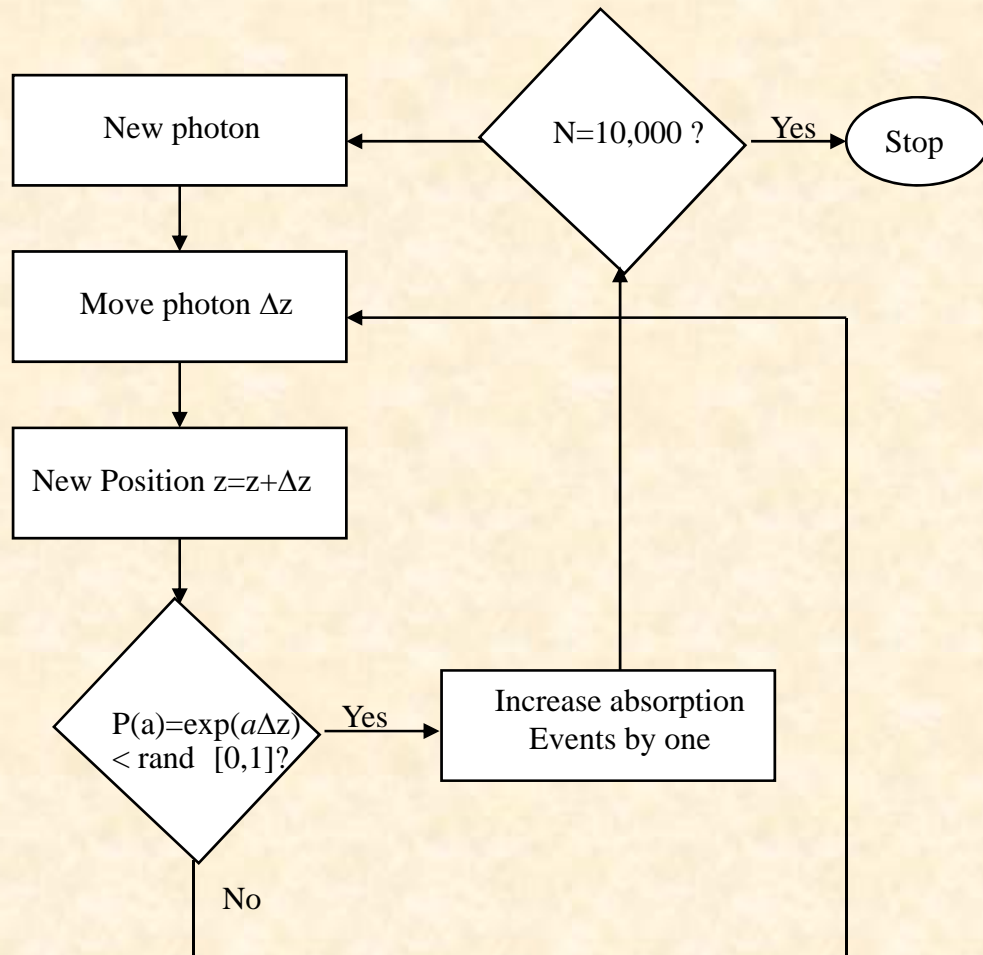


→ The probability of attenuation within the medium in the interval $[z, z + dz]$ is cdz , for $dz \ll 1/c$.

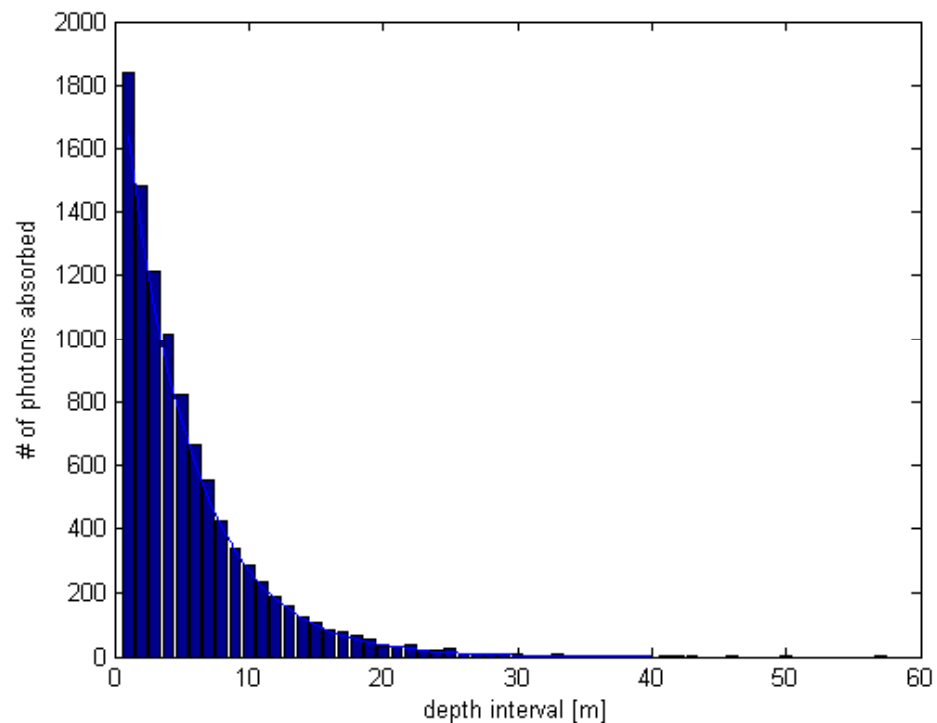
Concepts

- After moving a step, a photon is either absorbed, scattered or transmitted. However, to simplify the problem, we only consider absorption in this step, that is , no scattering occurs. Therefore, $c=a=1 \text{ m}^{-1}$ in this program.
- To simplify further, assume index matched boundary ($n_1=n_2$), fixed step, and fixed weight photon.
- Index matching means that no reflection occurs at the boundary.
- Fixed step means that absorption only happens at the end of a fixed step Δz . In the following program, $\Delta z=20 \text{ cm}$.
- Fixed weight photon means that a photon is treated as an integral particle. A photon cannot be partially absorbed.

Flow Chart



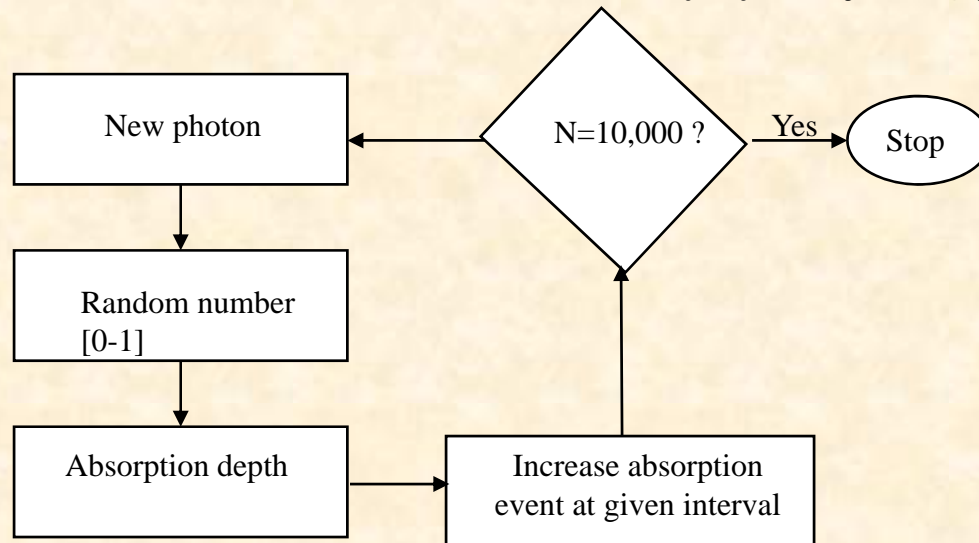
Results



Matlab program (code [MC_abs.m](#)):

```
a=1; %absorption [m^-1];
dz=0.2; %depth interval;
depths=[0:dz:20/a]; %depth discrization
interval=zeros(1,length(depths));
for i=1:10000
    k=1;
    while rand(1)>exp(a*dz)
        k=k+1;
    end
    interval(k)=interval(k)+1;
end
bar(interval);
hold on
plot([1:1:40],dz*10000*exp(-a*[1:1:40]*dz));
hold off
xlabel('depth interval')
ylabel('# of photons absorbed')
```

A better algorithm



Probability of absorption at depth between z and $z+dz$:

$$\exp(-az) \times (1 - \exp(-adz))$$

We can map $[0,1]$ to the depths photon reach:

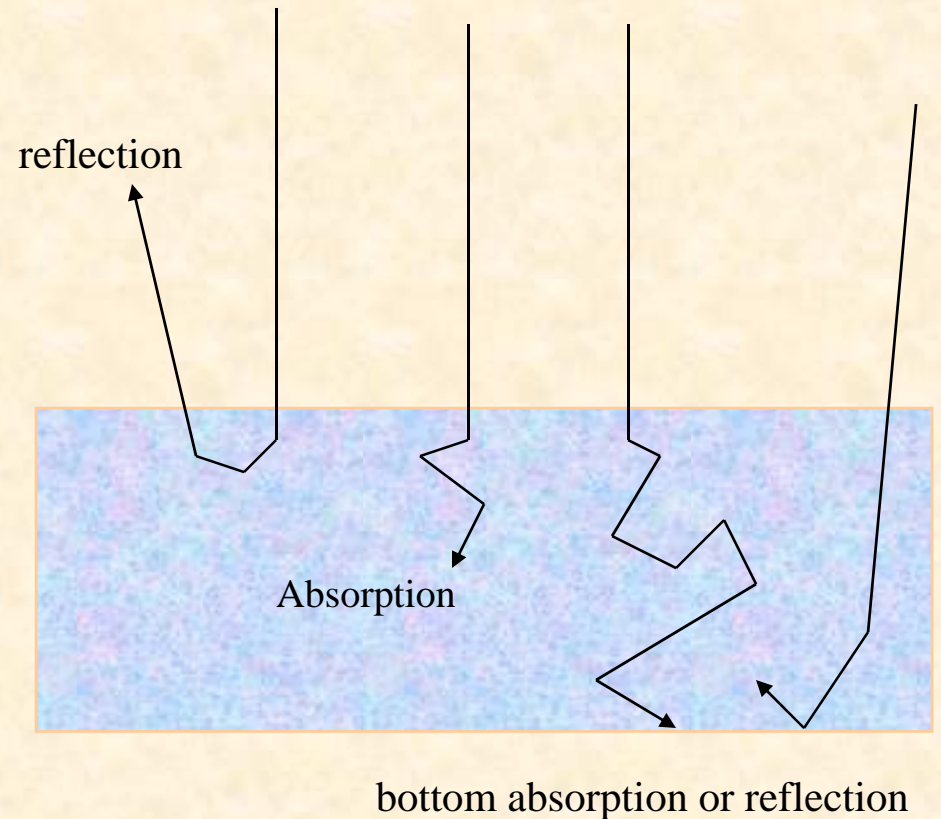
$$z(\text{abs}) = -\ln(1-r.n)/a = -\ln(r.n)/a$$

A single calculation per photon.

Code: **MC_abs.m** (2nd part)

Scattering of Photons in medium

- photons are either absorbed, transmitted through the medium or reflected back from the medium.
- We keep track of each photon and tally where all the photons terminate.
- Boundaries are index matched (can do it differently if needed).
- The step length of each photon is variable.



Concepts

- In this step we will simulate the scattering of a photon in the medium.
- Scattering is accomplished by accounting for the position and direction of each photon.
- If a photon exits the medium ($z < 0$), it has been reflected. Determining which depends on the z position at the exit point. At this point the photon is terminated (could be reflected back).
- Termination of the photon can also occur due to absorption in the medium or bottom.
- Step length is no longer a fixed value. It is calculated as:

$$z = -\log(r.n.)/c$$

Deflection Angle

- Deflection angle (θ) : When a photon is scattered it is deflected by this angle relative to its propagation direction:

$$\int_0^{\theta} \beta(\theta') \sin(\theta') d\theta' = \frac{b}{2\pi} \cdot \text{r.n.}$$

For empirical VSF use a lookup table and interpolation to save time on computations.

For certain idealized functions we have analytical expressions:

For Rayleigh, Raman and Pure-water scattering

$$-\frac{f}{6+2f}\mu^3 - \frac{3}{6+2f}\mu^2 + \frac{1}{2} - \xi = 0$$

Where $f=0.835$ for pure water 0.55 for Raman at 490nm and 1 for Rayleigh scattering. μ is the only positive root for a given ξ .

Henyey-Greenstein:

$$\mu_s = \frac{1}{2g} \left[1 + g^2 - \left(\frac{1 - g^2}{1 + g - 2g\xi} \right) \right]$$

Where $g>0$ is the asymmetry parameter

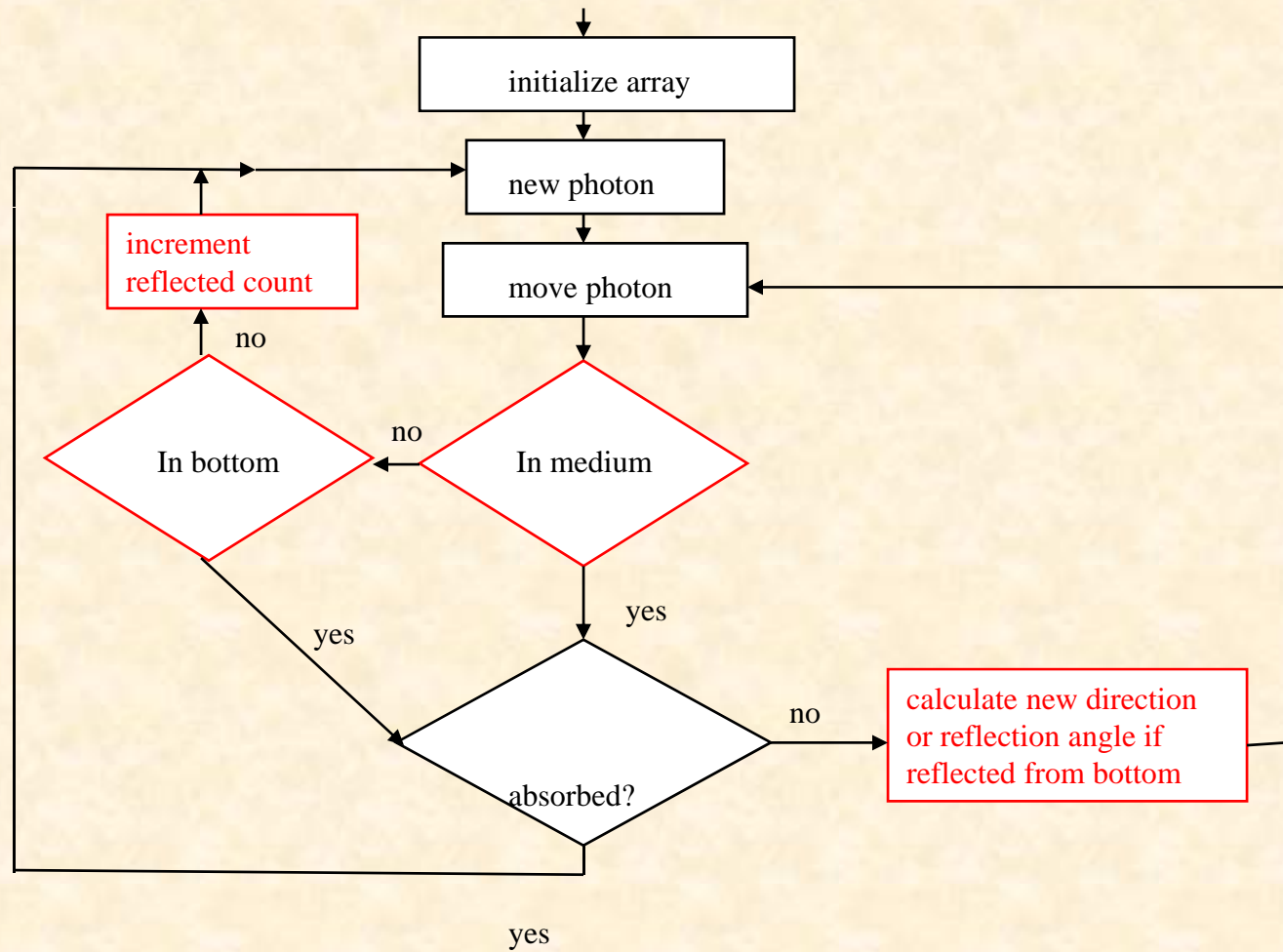
Program: Single_photon.m

Azimuthal Angle

- Azimuthal angle (ϕ) : When deflected by the Deflection angle, it is also deflected with respect to the orthogonal plane of propagation.

$$\phi = 2 * \pi * \text{r.n.}$$

Flow Chart



Variable Weight Photons

- Now, as a photon encounters the medium it's weight is decremented.
- Once the weight is small enough the photon will either terminate or be re-energized. A threshold is set to determine if the weight is significantly small.
- A photon is only re-energize every $1/\text{threshold}$ photons to keep the energy balanced. This concept is called roulette.

```
if(r.n. < threshold)
    weight = weight * 20;
else
    weight = 0;
```

Plane-Parallel semi infinite scattering medium illuminated from above:

```
c = 1; % attenuation coefficient (1/m)
w0 = 0.8; % single-scattering albedo
N = 1e5; % number of photons to trace
ns = 100; % max number of scatters per photon
E = 0; % initialize detector
for i=1:N
    z = 0; % initial position depth
    muz = 1; % incident light direction (collimated)
    w = 1; % initial photon weight
    for j=1:ns
        s = - log(rand)/c; % geometric path length
        z = z + muz*s; % move photon
        if (z<0) E=E+w; break, end % count photons leaving out top
        w=w*w0; % absorb fraction of photon packet
        muz= 1 - 2*rand; % isotopic scattering
    end
end
E = E/N % normalize result
```

See program: [semi-infinite.m](#)

Index Mismatch at boundary

- In this step, the index-mismatched boundary between air and water is taken into effect. When light enters water, the total reflectance R_t should include both the specular reflection R_{sp} and the remitted diffuse reflectance R_d .

Develop a Grid Structure

- To keep track of the locations at which photons are absorbed within the water.
- To accomplish this develop a two/three-dimensional array of bins corresponding to the depth/location of the photon.
- With each absorption event, the photon's weight will be added into the bin corresponding to the photon's current location.

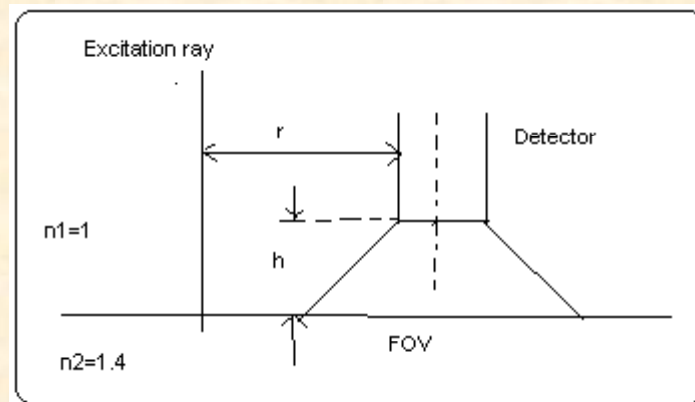
Detection of photons

Including a detector to detect the number of photons which enter the detector field of view.

- The detector is placed within the previously defined grid boundaries.

Detector Variables

- Detector position (Lateral distance from ray and the height above water)
- The detector radius
- The field of view of the detector (FOV)



Inverse Monte Carlo

- Use the principle of reciprocity: if a photon makes it from a to b, a photon can make it from b to a along the same path.
- Only simulates photons that made it to the detector (as opposed to the whole medium).

Monte Carlo vs. other RT

- MC is the most flexible of all RT can accommodate any arrangement of source, receiver and medium properties.
- MC is simple to conceptualize.
- MC is slow. Need to simulate millions of photons to reduce statistical error.

Monte Carlo Programming

A tutorial to Monte Carlo methods:

<http://people.revoledu.com/kardi/tutorial/Simulation/index.html>

List of tutorials:

<http://www.cooper.edu/engineering/chemechem/MMC/tutor.html>

Monte Carlo Simulation for Statistical Physics by Paul Coddington at Northeast Parallel Architectures Center at Syracuse University: An electronic book covering Monte Carlo programming in depth - includes discussion on Monte Carlo methods, specific algorithms, and problems and subtleties in Monte Carlo programming.

http://www.npac.syr.edu/users/paulc/lectures/montecarlo/p_montecarlo.html

Radiative transfer codes and documentation can also be found at:

<http://www-star.st-and.ac.uk/~kw25/research/montecarlo/montecarlo.html>