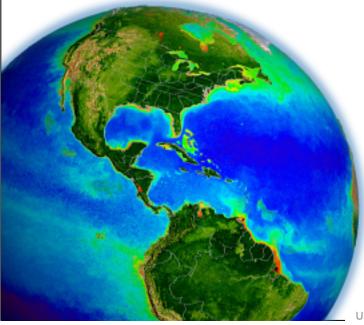
SeaDAS lab

Jeremy Werdell NASA Goddard Space Flight Center

UMaine Ocean Optics Summer Course Jul 7 – Aug 3, 2013

Acknowledgements: Aynur Abdurazik, Sean Bailey, Matt Elliot, Danny Knowles, & Don Shea





by the end of this lab, I hope you will ...

understand the organization & flow of satellite ocean color data

be comfortable with SeaDAS & without fear of breaking it

what is SeaDAS?

SeaWiFS Data Analysis System (SeaDAS) http://seadas.gsfc.nasa.gov http://oceancolor.gsfc.nasa.gov

image analysis package for processing, displaying, analyzing, & QC'ing satellite ocean color data

available for use with all NASA Ocean Biology Processing Group (OBPG) supported sensors: MODIS-Aqua & -Terra, SeaWiFS, OCTS,& CZCS, plus VIIRS, MERIS, HICO, etc.

general scientific imagery & data analysis package

why SeaDAS?

conceived of to fill a need in the post-CZCS, pre-SeaWiFS era when common tools did not exist to:

- display satellite ocean color data
- reproduce (& refine) the operational NASA products

still uncommon for agencies to distribute source code to replicate operational satellite data processing

SeaDAS development timeline

conceived of in the mid-1990's, referred to as "SeaPAK"

renamed "SeaDAS" circa the launch of SeaWiFS in 1997

stimulated development of the ESA BEAM software package to visualize ENVISAT (MERIS) data products circa 2002

awarded NASA Software of the Year in 2003

built on an IDL (Interactive Data Language) infrastructure through June 2012 (version 6.4)

recast as an integrated tool with the ESA BEAM software package in Spring 2013 (version 7)

SeaDAS 7

collaboration with BEAM (Brockmann Consult, Germany)

- look & feel of BEAM
- functionality & processing capabilities of SeaDAS 6.4

officially released in April 2013

this is the first training event!

we will break something at some point today – this is ok

lab organization

morning lecture: introduction & bookkeeping afternoon lecture: satellite data processing

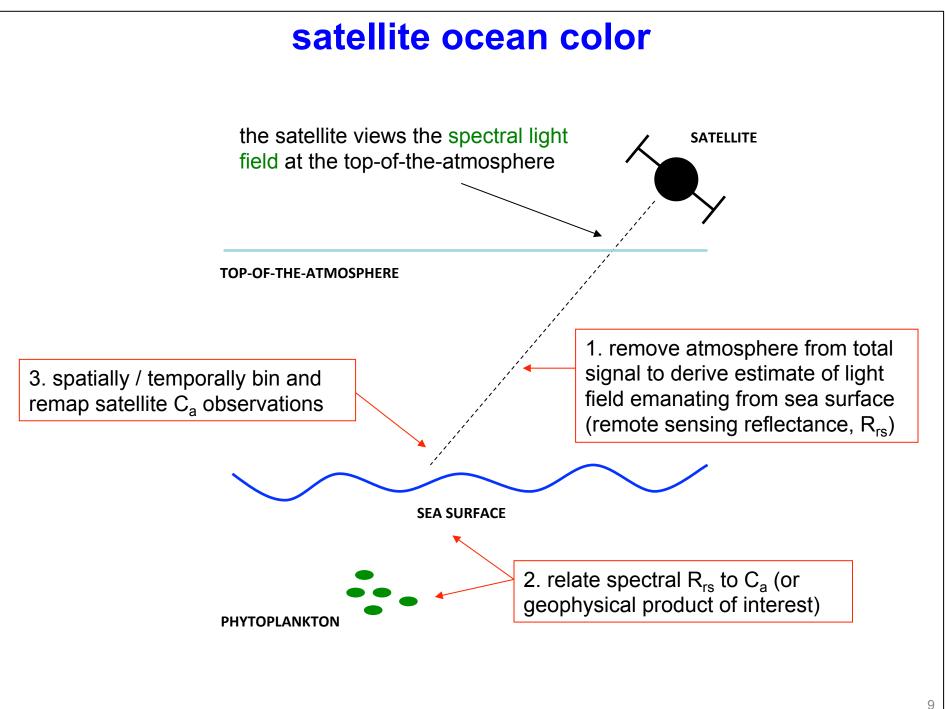
instructor-led demonstrations on:

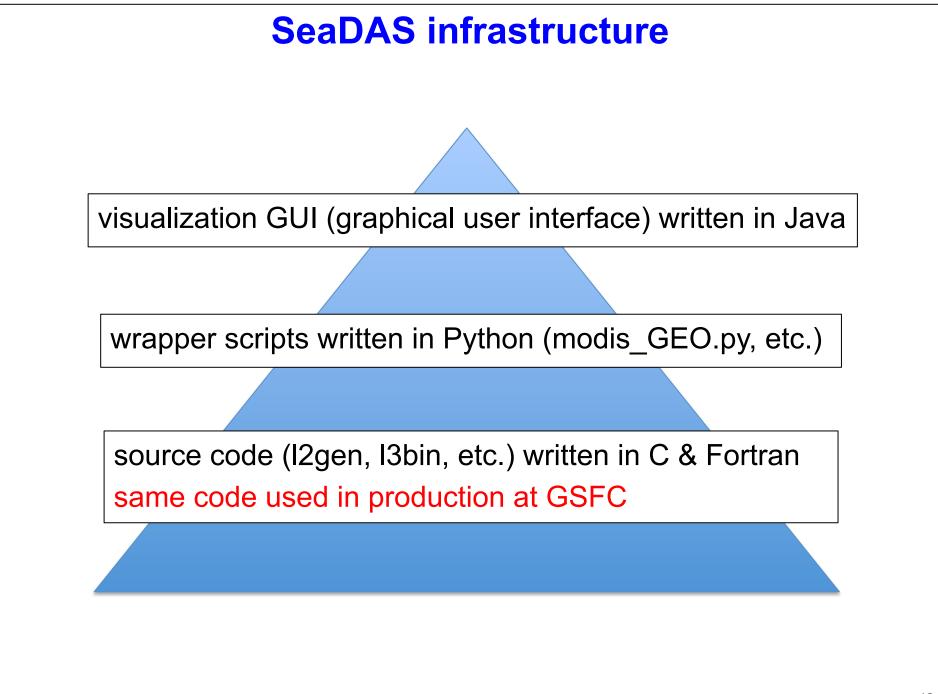
- the SeaDAS environment & visualizing data
- flags & masks
- data analysis tools
- satellite data processing
- comparing satellite & in situ measurements

student exercises following each demonstration

has anyone used SeaDAS 6 or 7 before?

what would you like to learn to do in SeaDAS 7?





requirements

SeaDAS 7.0 is currently available for Linux, Mac OS X, and Windows. The Windows version currently does not support the science data processing code. The SeaDAS source code is publicly available.

Suggested Hardware Requirements:

Platforms:	Linux Intel Mac OS X		
Memory:	256MB minimum, 1GB+ suggested		
Disk:	SeaDAS software package (display only version): ~200MB SeaDAS software package (with processing capabilities for all sensors): ~5B 10GB of free space is also suggested for rudimentary data processing and storage.		
Display:	15" Console or X-terminal with 20MB memory 1280x1024 resolution 24-bit X display plane depth 256 colors display minimum		

Requirements:

The core visualization package of SeaDAS 7 is written in Java. A minimum Java JRE of version 1.6 is required. A suitable JRE is packaged with the Windows distributions. The MacOSX distribution relies on the Apple delivered Java

Operating	y Systems:	Linux: tested on various versions of CentOS, Fedora, and Ubuntu Intel Mac: OS X 10.7 and 10.8
Optional	Compilers:	gcc/g++/gfortran (version 4.5 or higher) or Intel Compilers
Program	Version	Notes
Java	JRE 1.6 or above	Windows distributions comes with a suitable JRE; MacOSX uses the Apple default JRE
Bash	4.x	version 3.x should work, but not tested necessary only for science code, thus not required for Windows distributions
Python	2.6.5 or above	necessary only for science code, thus not required for Windows distributions; not (yet) compatible with version 3 and above
Git	1.7.x or above	necessary only for science code install/update option, thus not required for Windows distributions
cURL	7.x or above	necessary only for science code install/update option, thus not required for Windows distributions

satellite ocean color file formats

HDF & netCDF http://www.hdfgroup.org/ http://www.unidata.ucar.edu/software/netcdf/

self-describing & machine independent file structure

layers of array-oriented data proceeded by global attributes that describe the data & provide metadata

SeaDAS resources

SeaDAS Web site – online help & instructions http://seadas.gsfc.nasa.gov

OceanColor online forum – SeaDAS-specific boards <u>http://oceancolor.gsfc.nasa.gov/forum/oceancolor/forum_show.pl</u>

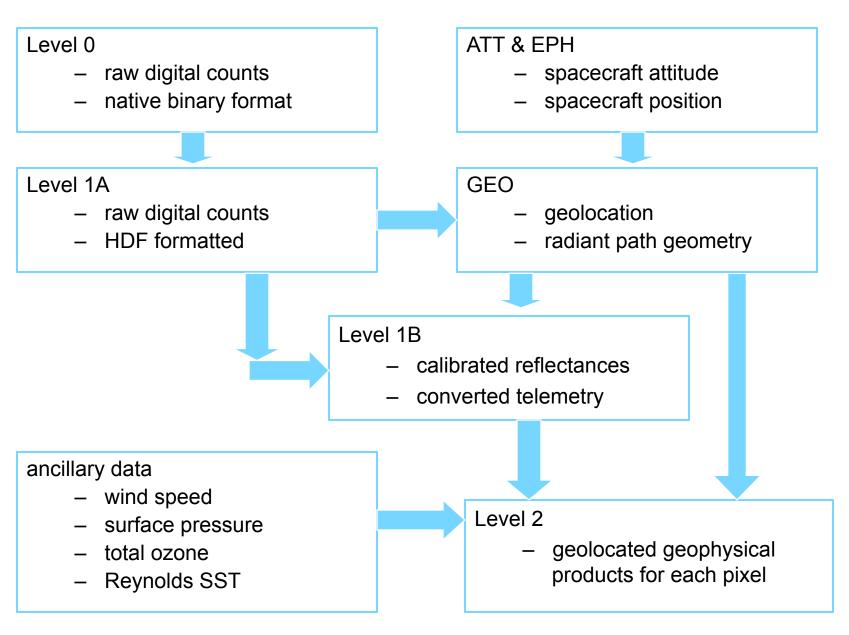
SeaDAS 7 interactive help (buttons within the GUI)

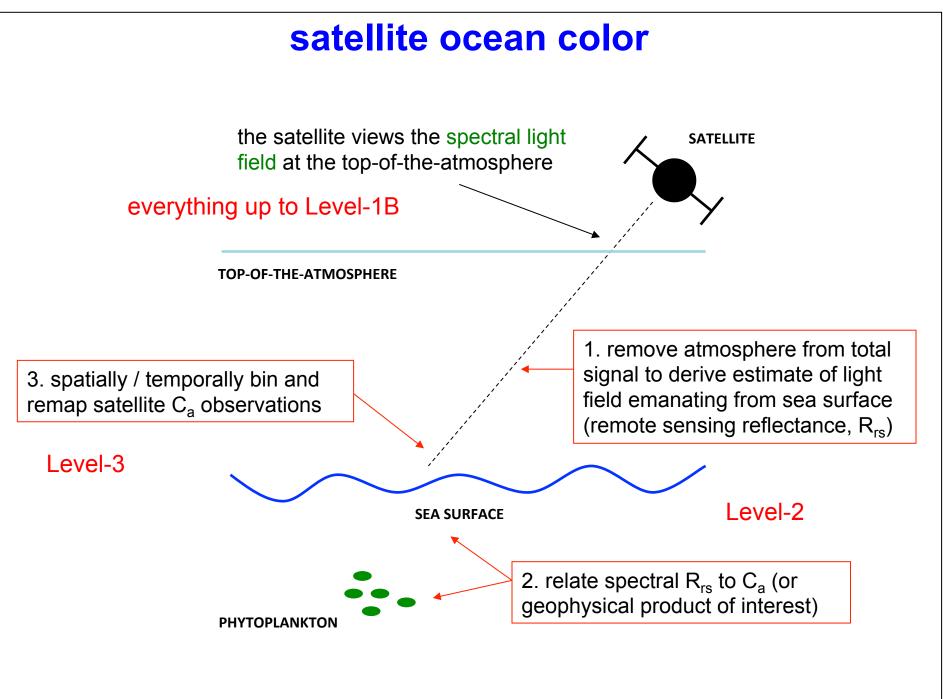
email

seadas@seadas.gsfc.nasa.gov

lecture break

MODIS data levels & flow



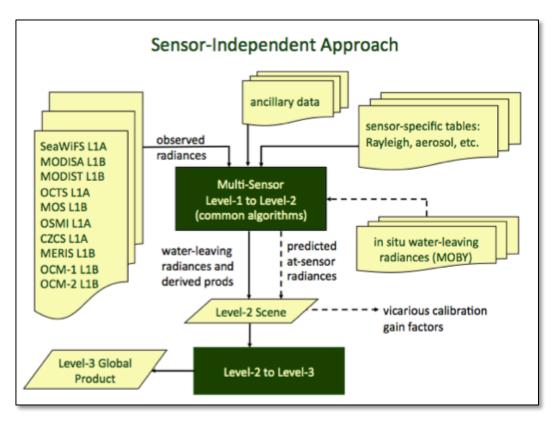


Level-2 processing (l2gen)

common software for Level-2 processing of MODIS, SeaWiFS, MERIS, & other sensors in a consistent manner

supports a multitude of product algorithms and processing methodologies

- standard products
- evaluation products
- user defined products
- run-time selection



Level-2 processing (l2gen)

as data is processed by l2gen from Level 1 to Level 2, checks are made for different defined conditions

when certain tests and conditions are met for a given pixel, a flag is set for that pixel for that condition

a total of 31 flags can be set for each pixel

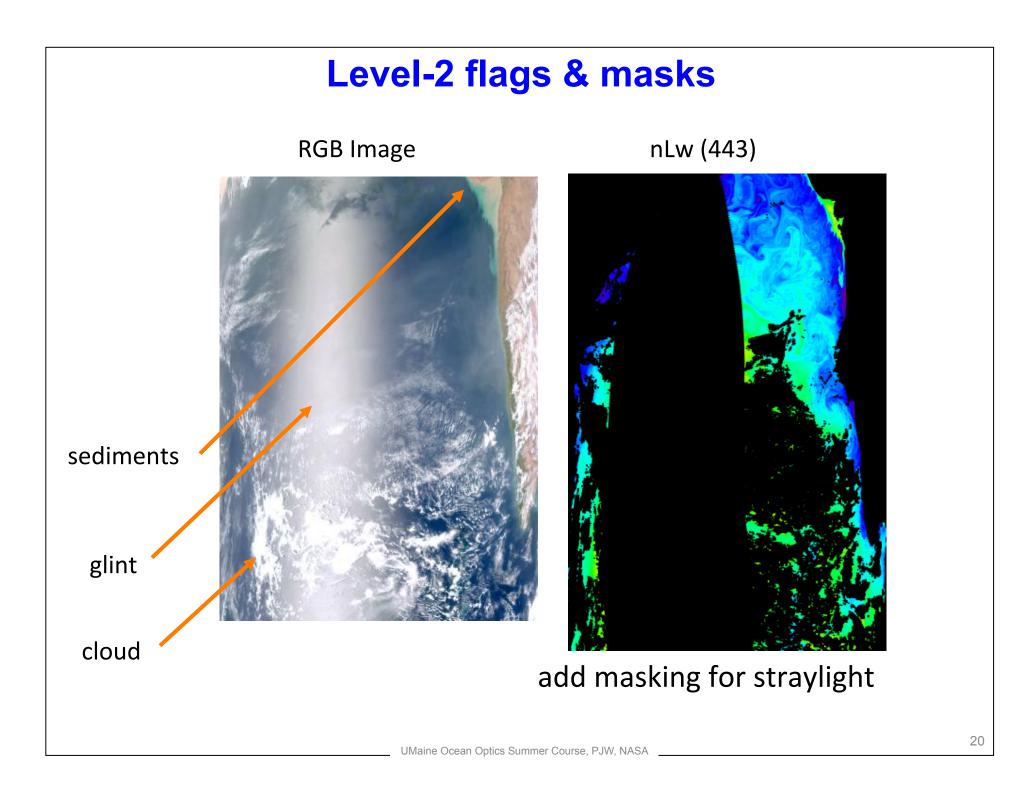
these I2gen processing flags are stored in the Level 2 data file as the "I2_flags" product

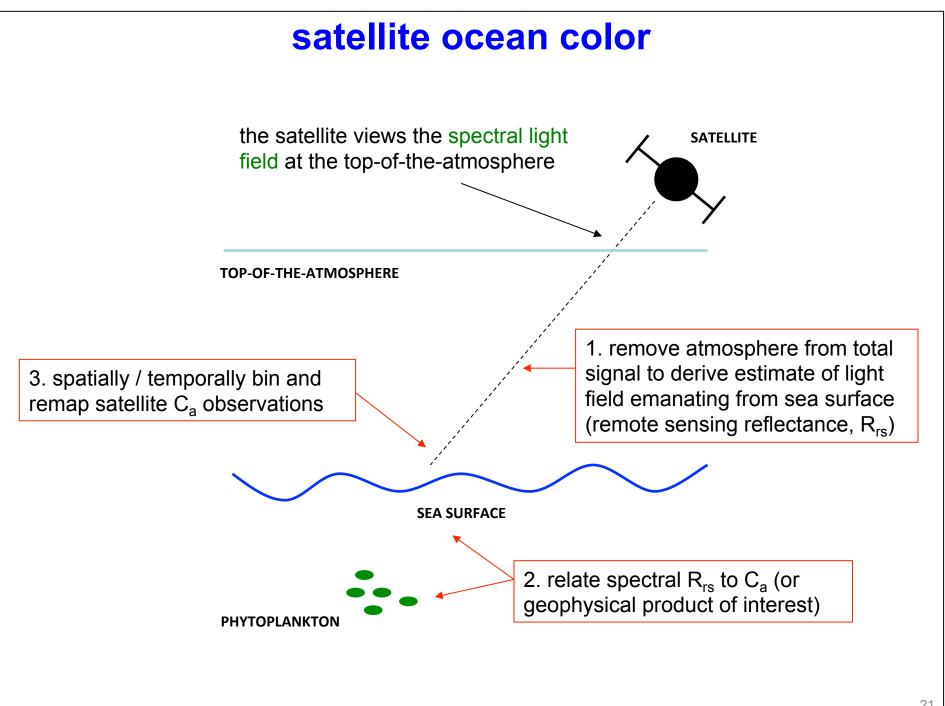
the storage method sets bits to 0 or 1 in 32-bit integers that correspond to each pixel

Level-2 processing flags

Bit Name	Description
01 ATMFAIL	Atmospheric correction failure
02 LAND	Pixel is over land
03 BADANC	Reduced quality of ancillary data
04 HIGLINT	High sun glint
05 HILT	Observed radiance very high or saturated
06 HISATZEN	High sensor view zenith angle
07 COASTZ	Pixel is in shallow water
08 NEGLW	Negative water-leaving radiance retrieved
09 STRAYLIGHT	Straylight contamination is likely
10 CLDICE	Probable cloud or ice contamination
11 COCCOLITH	Coccolithofores detected
12 TURBIDW	Turbid water detected
13 HISOLZEN	High solar zenith
14 HITAU	High aerosol optical thickness
15 LOWLW	Very low water-leaving radiance (cloud shadow)
16 CHLFAIL	Derived product algorithm failure

Bit	Name	Description
17	NAVWARN	Navigation quality is reduced
18	ABSAER	possible absorbing aerosol (disabled)
19	TRICHO	Possible trichodesmium contamination
20	MAXAERITER	Aerosol iterations exceeded max
21	MODGLINT	Moderate sun glint contamination
22	CHLWARN	Derived product quality is reduced
23	ATMWARN	Atmospheric correction is suspect
24	DARKPIXEL	Rayleigh-subtraced radiances is negative
25	SEAICE	Possible sea ice contamination
26	NAVFAIL	Bad navigation
27	FILTER	Pixel rejected by user-defined filter
28	SSTWARN	SST quality is reduced
29	SSTFAIL	SST quality is bad
30	HIPOL	High degree of polarization
31	spare	spare
32	OCEAN	not cloud or land





MODIS Level-3 processing

Level 2

 geolocated geophysical products for each pixel

Level 3 binned

- geophysical products averaged spatially and/or temporally
- sinusoidally distributed, equal area bins

Level 3 mapped

- images created by mapping and scaling binned products
- user-friendly, cylindrical equiangular projection

Bin resolution 4.6 x 4.6 km²

Mapped resolution

- 0.042-deg
- 0.084-deg

Composite Periods

- Daily
- 8-day
- Monthly
- Seasonal
- Yearly
- Mission

Level-3 terminology

projection - any process which transforms a spatially organized data set from one coordinate system to another

mapping - process of transforming a data set from an arbitrary spatial organization to a uniform (rectangular, row-by-column) organization, by processes of projection & resampling

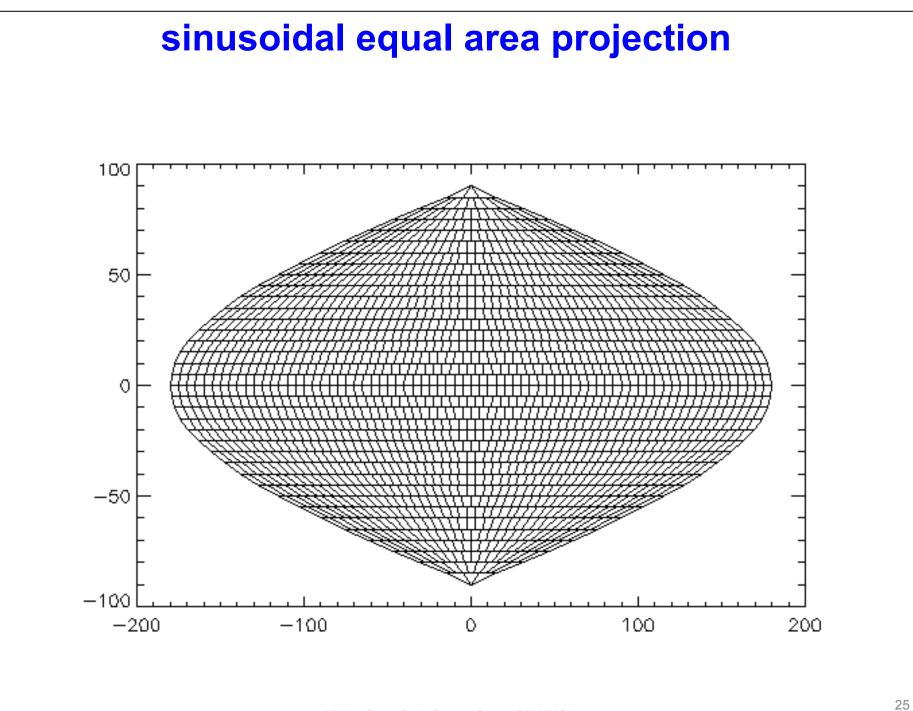
binning - process of projecting & aggregating data from an arbitrary spatial & temporal organization to a uniform spatial scale over a defined time range

ocean color projections

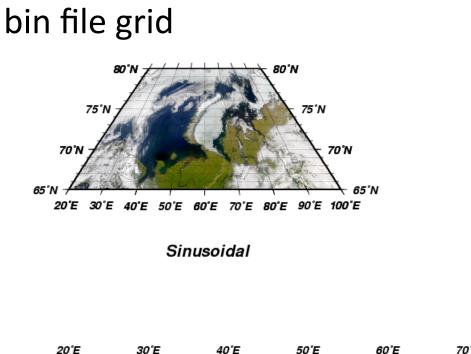
equal-area - sinusoidal with equally space rows & number of bins per row proportional to sine of latitude

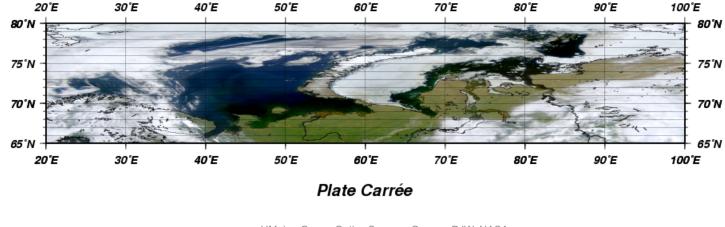
equal-angle - rectangular (Platte Carre) with rows and columns equally spaced in latitude and longitude

equal-area & -angle projections are equivalent at the equator

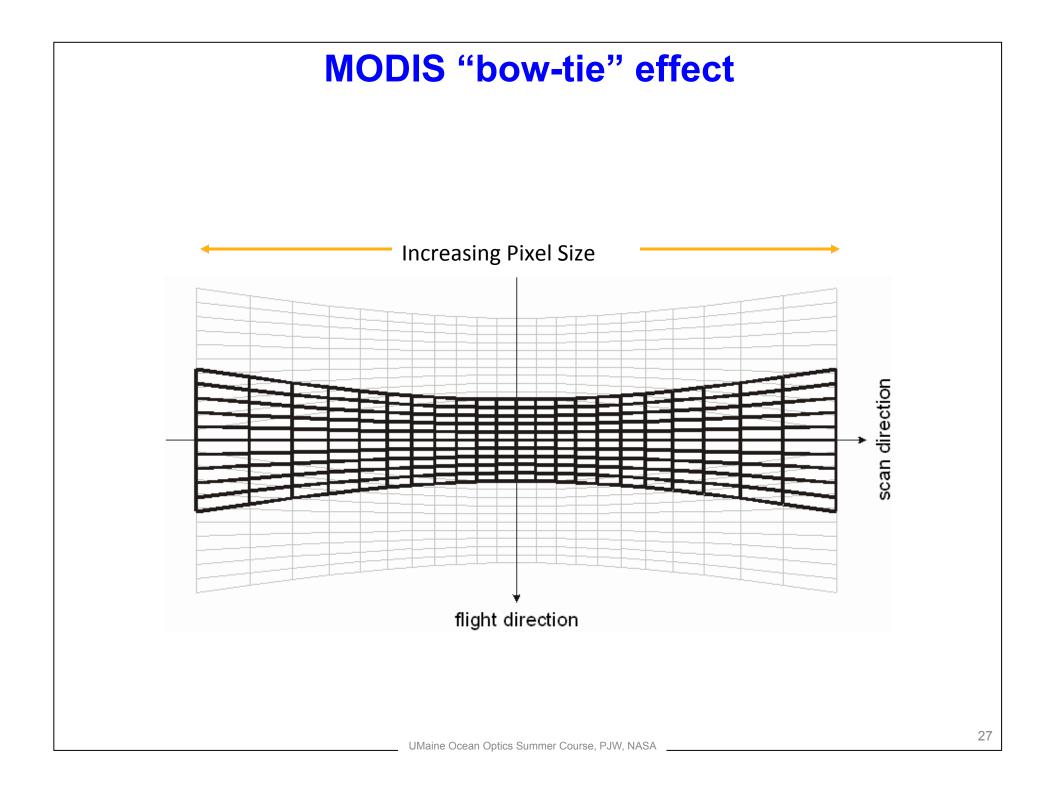


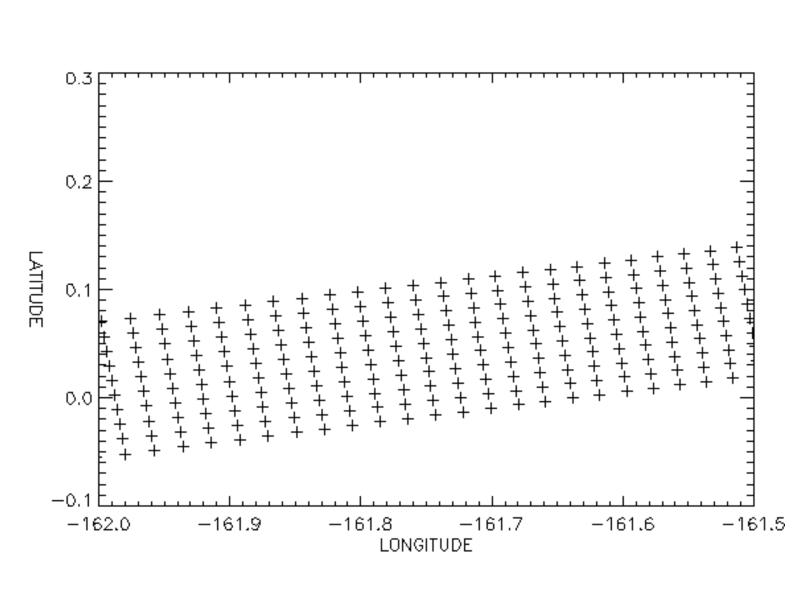
Level-3 binned vs. mapped



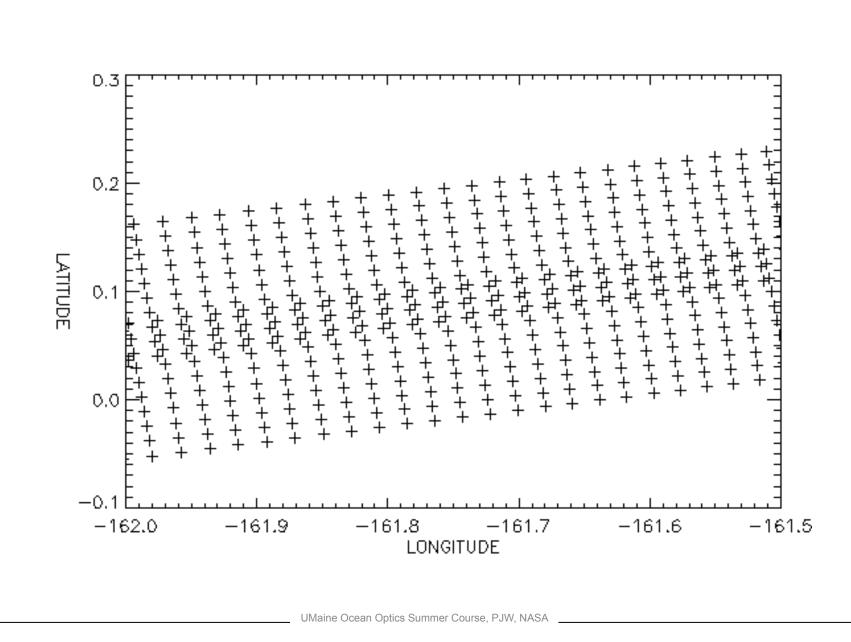


map file grid



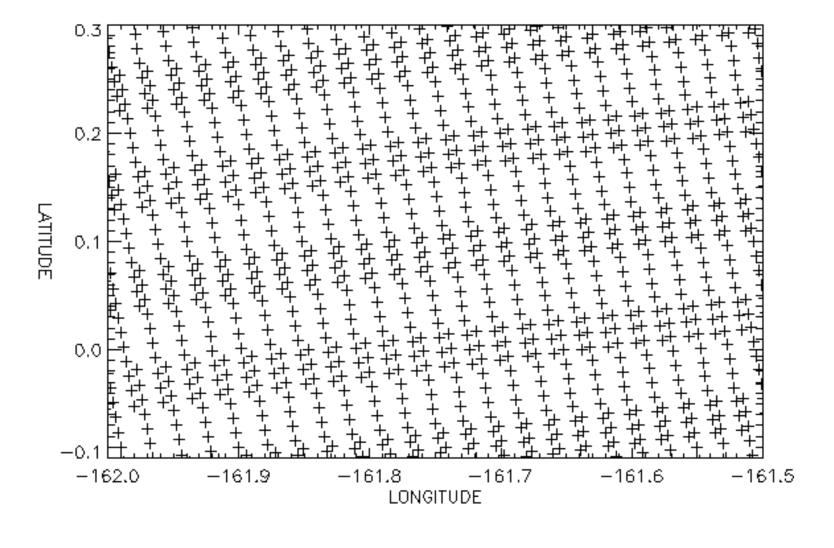


one MODIS scan at ~45 degrees scan angle

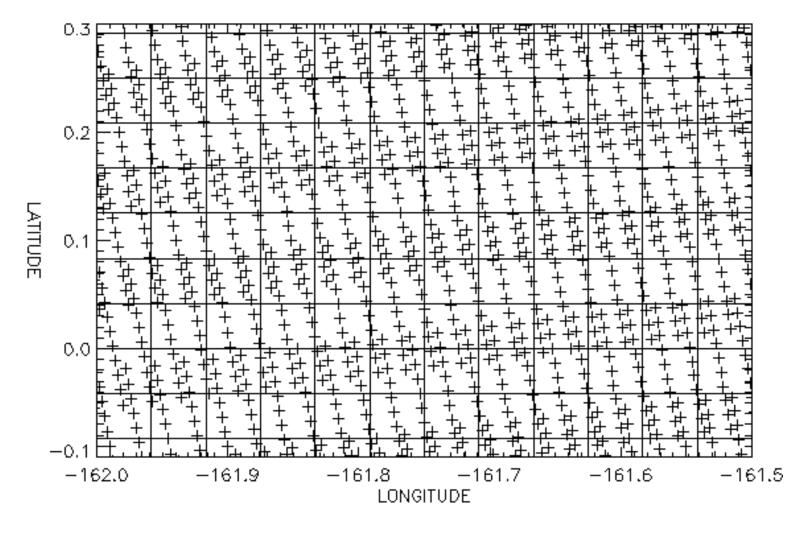


two MODIS scans showing overlap of pixels

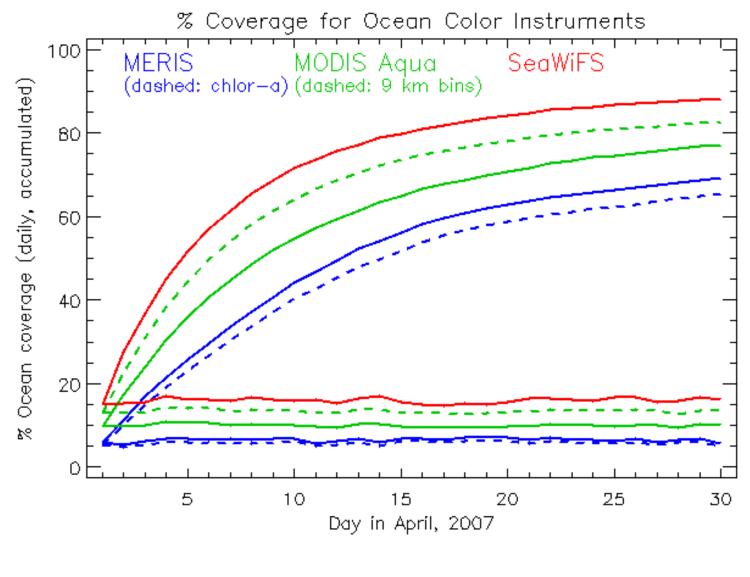
multiple MODIS scans showing pixel overlap



bin boundaries overlaid on pixel locations

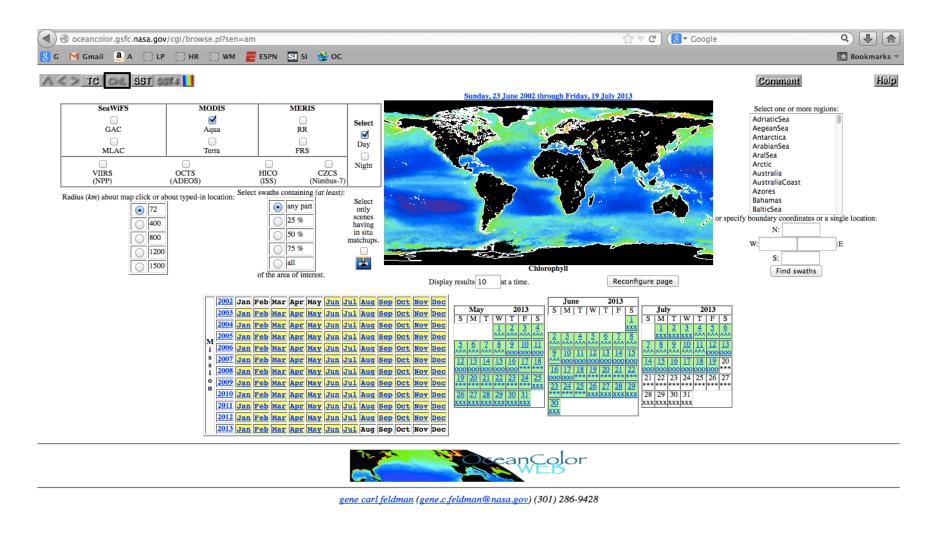


ocean coverage over time for binned files



lecture break

acquiring ocean color data



http://oceancolor.gsfc.nasa.gov/cgi/browse.pl