#### SBE 16plus V2 (RS-232) SEACAT Reference Sheet (see SBE 16plus V2 [RS-232] User's Manual for complete details)

### Sampling Modes

- Autonomous sampling The 16*plus* V2 takes time series measurements once every 10 seconds to once every 4 hours, stores data in FLASH memory, and powers down between samples. Data can also be simultaneously transmitted real-time.
- **Polled sampling** The 16*plus* V2 takes one sample. Depending on command used, the 16*plus* V2 can store data in FLASH memory and / or transmit data to computer.
- Serial line sync The 16plus V2 wakes up, samples, stores data in FLASH memory, and powers off in response to a pulse on serial line. Depending on setup, the 16plus V2 can transmit data to computer. This provides an easy method for synchronizing 16plus V2 sampling with other instruments such as Acoustic Doppler Current Profilers (ADCPs) or current meters, without drawing on their battery or memory resources.

#### Setup

- 1. Double click on SeatermV2.exe. SeatermV2 opens, select SBE 16plus V2 RS232. Seaterm232 opens.
- 2. In the Communications menu, select Configure. Select the Comm port and baud rate (factory set to 9600), and click OK.
- 3. Seaterm232 should automatically connect to the 16*plus* V2. As it connects, it sends **GetHD** and displays the response, and then fills the Send Commands window with the list of commands for your 16*plus* V2.
- 4. Program 16plus V2 for intended deployment (see other side of this sheet for *Command Instructions and List*)
  A. Ensure all data has been uploaded, and then send **InitLogging** to make entire memory available for recording. If **InitLogging** is not sent, data will be stored after last recorded sample.
  - B. Send DateTime=mmddyyyyhhmmss (month, day, year, hour, minute, second) to set date and time.
  - C. Establish setup and sampling parameters. If desired, use **StartDateTime=** and **StartLater** to establish delayed start date and time.

## Deployment

- 1. Batteries:
  - A. *Remove battery end cap*: Wipe dry housing/end cap seam. Unthread end cap by rotating counter-clockwise. Wipe dry O-ring mating surfaces in housing with lint-free cloth.
  - B. *Remove and replace battery cover plate and batteries*: Remove three Phillips-head screws and washers from battery cover plate, and remove cover plate. Turn 16*plus* V2 over and remove batteries. Install new batteries, + terminals against flat contacts and terminals against spring contacts. Align battery cover plate with housing. Reinstall three Phillips-head screws and washers, while pushing hard on battery cover plate to depress spring contacts at bottom of battery compartment.
  - C. *Reinstall battery end cap*: Remove water from O-rings and mating surfaces with lint-free cloth. Inspect O-rings and mating surfaces for dirt, nicks, and cuts. Clean/replace as necessary. Apply light coat of O-ring lubricant to O-ring and mating surfaces. Fit end cap into housing and rethread into place, using a wrench to ensure end cap is tightly secured.
- 2. Install a cable or dummy plug for each connector on 16 plus V2 sensor end cap. Install a locking sleeve over each plug/cable connector. Connect other end of cables to appropriate sensors.
- 3. Verify hardware and external fittings are secure.
- 4. Remove Tygon tubing that is looped end-to-end around conductivity cell.
- 5. For Autonomous sampling: If not already done, send StartNow or send StartDateTime= and StartLater.

# Data Upload

- 1. Double click on SeatermV2.exe. SeatermV2 opens, select SBE 16plus V2 RS232. Seaterm232 opens.
- 2. In the Communications menu, select Configure. Select the Comm port and baud rate (factory set to 9600), and click OK.
- 3. Seaterm232 should automatically connect to the 16*plus* V2. As it connects, it sends **GetHD** and displays the response, and then fills the Send Commands window with the list of commands for your 16*plus* V2.
- 4. If sampling autonomously (logging), command 16plus V2 to stop logging by sending Stop.
- 5. Click Upload menu to upload stored data.
- 6. Run SBE Data Processing to convert uploaded .hex file to .cnv file for use by other modules in data processing software. Process file and review data to ensure all data has been uploaded.

## **Command Instructions and List**

- Input commands in upper or lower case letters and register commands by pressing Enter key.
- 16*plus* V2 sends an error message if an invalid command is entered.
- (if OutputExecutedTag=N) If 16plus V2 does not return S> prompt after executing a command, press Enter key to get S>.
- If new command is not received within 2 minutes after completion of a command, 16plus V2 returns to quiescent (sleep) state.

• If in quiescent (sleep) state, re-establish communications by clicking Connect in Communications menu or pressing Enter key.

Shown below are the commands used most commonly in the field. See the Manual for complete listing and detailed descriptions.

CATEGORY	C	COMMAND			DESCRIPTION			
	GetCD				Get and display Configuration Data.			
Status		GetSD			Get and display Status Data.			
	GetCC				Get and display Calibration Coefficients.			
	GetEC				Get and display Event Counters.			
	ResetEC				Reset Event Counters.			
	GetHD				Get and display Hardware Data.			
	DS				Display status and setup parameters.			
	DCal				Display calibration coefficients.			
General Setup	DateTime=mmddyyyyhhmmss			hmmss	Set real-time clock month, day, year, hour, minute, second.			
	BaudRate=x				<b>x</b> = baud (600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200). Default 9600.			
	Echo=x				x=Y: Echo characters as you type.	x=N: Do not.		
	OutputExecutedTag=x			g=x	x=Y: Display XML Executing and Executed tags.	x=N: Do not.		
	TxRealTime=x				<b>x=Y</b> : Output real-time data for autonomous sampling and serial line sync.	x=N: Do not.		
	PumpMode=x				x=0: No pump.x=1: Run pump for 0.5 seconds before each sample.x=2: Run pump during each sample.			
	NCycles=x				$\mathbf{x}$ = number of measurements to take and average for every sample.			
	InitLogging				After uploading data, initialize logging to make entire memory available for recording.			
	BioWiper=x				$\mathbf{x}=\mathbf{Y}$ : Configuration includes WET Labs sensor with Bio-Wiper.	K=N: Does not.		
	OS				Place in quiescent (sleep) state. Logging and memory retention not affected.			
Pressure					x=0: No pressure. $x=1$ : Strain gauge pressure sensor.			
Sensor Setup	PType=x				x = 3: Quartz pressure sensor with temperature compensation.	ssure sensor.		
(internally	RefPress=x			$\mathbf{x}$ = reference pressure (gauge) in db to use if 16 <i>plus</i> V2 does not include pressure sense	sor.			
mounted)	ParosIntegration=x		x	$\mathbf{x}$ = integration time (seconds) for Quartz pressure sensor.				
mounica)		Volt1=		Volt2=x				
		Volt4=		Volt5=x				
		DelayBeforeSampling=x			<b>x</b> = time (sec) to wait after switching on external voltage and RS-232 sensors before sampling.			
	DelayAfterSampling=x				<b>x</b> = time (sec) to wait after sampling complete, before turning off power to external voltage and RS-232 sensors.			
	SBE63=x				x=Y: Enable SBE 63 optical dissolved oxygen sensor.	x=N: Do not.		
RS-232 Sensor Setup	SBE05=x SBE38=x				x=Y: Enable SBE 38 secondary temperature sensor.	x=N: Do not.		
	SBE38=x SBE50=x				x=Y: Enable SBE 50 pressure sensor.	x=N: Do not.		
	WetLabs=x				$\mathbf{x} = \mathbf{Y}$ : Enable WET Labs RS-232 sensor.	x=N: Do not.		
	GTD=x				<b>x=Y</b> : Enable GTD (Pro-Oceanus Gas Tension Device).	x=N: Do not.		
	DualGTD=x				<b>x=Y</b> : Enable dual (2) GTDs (Pro-Oceanus Gas Tension Devices).	x=N: Do not.		
					Measure Gas Tension Device(s), output 1 converted data sample for each GTD.	A IV. Do not.		
	Optode=x				$\mathbf{x}=\mathbf{Y}$ : Enable Aanderaa Optode. $\mathbf{x}=\mathbf{N}$ : De	o not		
Output Format	OutputFormat=x					rted data, Hex.		
					<b>x=2</b> : Raw frequencies/voltages, decimal. <b>x=3</b> : Converted			
					x=4: Not valid format; do not use. x=5: Converted data, c			
	OutputSal=x				<b>x=Y</b> : Output salinity (psu).	x=N: Do not.		
	OutputSV=x				<b>x=Y</b> : Output sound velocity (m/sec).	x=N: Do not.		
	OutputUCSD=x				<b>x=Y</b> : Output sigma-t (kg/m <sup>3</sup> ), battery voltage, operating current (mA).	x=N: Do not.		
Autonomous Sampling (logging)		SampleInterval=x			$\mathbf{x}$ = interval between samples (10 - 14,400 seconds).			
	StartNow				Start autonomous sampling now.			
	StartDateTime=mmddyyyyhhmmss			yhhmmss	Delayed start: month, day, year, hour, minute, second.			
	StartLater				Start autonomous sampling at delayed start time.			
	Stop				Stop autonomous sampling or waiting to start autonomous sampling. Press Enter key command. Must stop sampling before uploading data.	before entering		
Polled Sampling	SL				Output last sample from buffer and leave power on.			
	SLT				Output last sample from buffer, take new sample and store data in buffer. Leave power on.			
	TS				Take sample, store in buffer, output data. Leave power on.			
	TSS				Take sample, store in buffer and FLASH memory, output data, turn power off.			
	TSSOn				Take sample, store in buffer and FLASH memory, output data, leave power on.			
		TSSO	า			Output last x samples from FLASH memory.		
	GetI	<u>TSSOr</u> LastSam		ĸ				
Serial Line			ples:x	ĸ		<b>x=N</b> : Do not.		
Serial Line Sync	Sy	LastSam	nples:x le=x	ĸ	Output last x samples from FLASH memory.			
	Sy	LastSam yncMod yncWai	nples:x le=x	x DDb,e	Output last x samples from FLASH memory. x=Y: Enable serial line sync mode.			