# **MicroCAT C-T Sensor** (Serial Interface & integral Pump)

The SBE 37-SIP MicroCAT is a high-accuracy conductivity and temperature (pressure optional) sensor with Serial Interface and integral Pump, which includes a non-volatile FLASH memory. Externally powered, it is intended for moorings or other long-duration, fixed-site deployments. Constructed of titanium and other non-corroding materials to ensure long life with minimum maintenance, the MicroCAT's depth capability is 7000 meters; it is also available with an optional 250-meter plastic ShallowCAThousing.

Calibration coefficients are stored in EEPROM, allowing the MicroCAT to output data in ASCII engineering units (decimal or XML format); raw output is also available. The data always includes Conductivity. Temperature, and Pressure (if optional pressure sensor installed); users can choose to add any combination of time, sound velocity (Chen-Millero), salinity, depth, and density.

The MicroCAT retains the temperature and conductivity sensors used in our time-proven SEACAT and SEACAT plus products. Electrical isolation of the conductivity electronics eliminates any possibility of ground-loop noise. The MicroCAT's unique internal-field conductivity cell permits the use of expendable anti-foulant devices. Its aged and pressure-protected thermistor has a long history of exceptional accuracy and stability.

The optional Druck pressure sensor has a superior design that is entirely different from conventional 'silicon' types in which the deflection of a metallic diaphragm is detected by epoxy-bonded silicon strain gauges. The Druck sensor employs a micro-machined silicon diaphragm into which the strain elements are implanted using semiconductor fabrication techniques. Unlike metal diaphragms, silicon's crystal structure is perfectly elastic, so the sensor is essentially free of pressure hysteresis. Compensation of the temperature influence on pressure offset and scale is performed by the MicroCAT's CPU.

### SENSOR INTERFACE ELECTRONICS

Temperature is acquired by applying an AC excitation to a hermetically sealed VISHAY reference resistor and an ultra-stable aged thermistor (drift rate typically less than 0.002 °C per year). The ratio of thermistor

resistance to reference resistance is determined by a 24-bit A/D converter; this A/D also processes the pressure sensor signal. Conductivity is acquired using an ultra-precision Wien-Bridge oscillator.

#### PUMP

The integral pump typically runs for 1.0 second each time the MicroCAT samples, providing the following advantages:

- Improved conductivity response The pump flushes the previously sampled water from the conductivity cell and brings a new water sample quickly into the cell.
- Improved anti-foul protection Water does not freely flow through the conductivity cell between samples, allowing the anti-foul concentration inside the cell to build up.

#### **COMMUNICATIONS AND INTERFACING**

The MicroCAT communicates directly with a computer via a standard RS-232 serial interface. Real-time data can be transmitted up to 1600 meters (5200 feet) at 600 baud (power considerations may limit distance), simultaneous with recording. Data can be uploaded at up to 115.2K baud. Firmware upgrades can be downloaded through the communications port by the user, without opening the instrument. An optional RS-485 interface allows multiple MicroCATs to share a common 4-wire cable (power, common, data +, data - ), minimizing cable complexity for C-T chains.

User-selectable operating modes include:

- Autonomous Sampling The MicroCAT is pre-programmed to sample, store data in FLASH memory, and transmit data. There are two types of autonomous sampling:
  - Continuous sampling at the fastest rate possible (1.0 second minimum without pressure), with the pump running continuously - Interval sampling at intervals of 6 seconds to 4 hours, with the pump running before each sample.
- Polled Sampling On command from a computer or satellite, radio, or wire telemetry equipment, the MicroCAT runs the pump, takes a sample, and transmits data.
- Serial Line Sync In response to a pulse on the serial line, the MicroCAT wakes up, runs the pump, samples, stores data in FLASH memory, transmits data, and goes to sleep.

#### SOFTWARE

The MicroCAT is supplied with a powerful Windows 2000/XP software package, SEASOFT<sup>®</sup> V2, which includes:

- SeatermV2<sup>©</sup> terminal program for easy communication and data retrieval.
- SBE Data Processing<sup>®</sup> programs for calculation, display, and plotting of conductivity, temperature, pressure (optional), and derived variables such as salinity and sound velocity.



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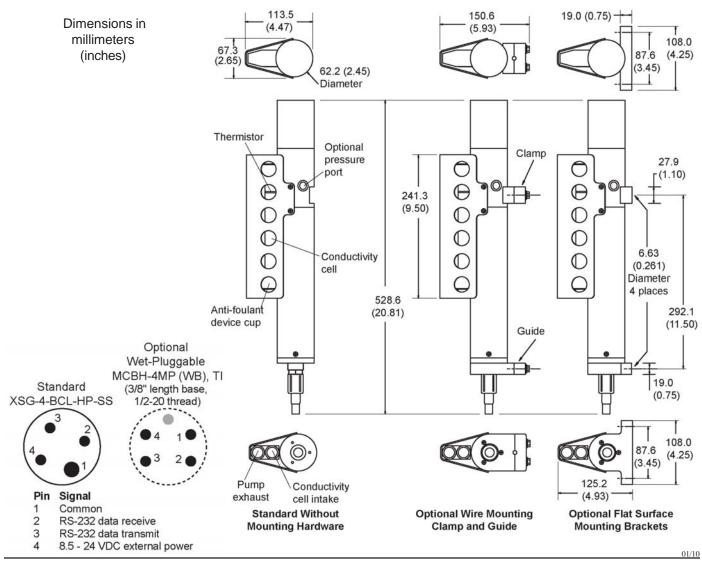




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SPECIFICATIONS			
Measurement Range		Clock Stability	5 seconds/month
Conductivity:	0 - 7 S/m (0 - 70 mS/cm)	Memory	8 Mbyte; capacity in excess
Temperature:	-5 to 35 °C		of 530,000 samples
Optional Pressure: 20/100/350/600/1000/2000/3500/7000		Input Power	0.5 Amps at 8.5 - 24 VDC
	(meters of deployment depth capability)	Quiescent Current*	30 microAmps
Initial Accuracy		Communication Current*	4.3 milliAmps
Conductivity:	0.0003 S/m (0.003 mS/cm)	Acquisition Current*	15 milliAmps (excluding pump)
Temperature:	0.002 °C	Acquisition Time	1.0 - 2.6 seconds/sample,
Optional Pressure: 0.1% of full scale range			dependent on sampling mode
Typical Stability			and inclusion of pressure sensor
Conductivity:	0.0003 S/m (0.003 mS/cm) per month	Pump Current	260 milliAmps
Temperature:	0.0002 °C per month	Housing, Depth Rating,	& Weight (without pressure or clamps)
Optional Pressure: 0.05% of full scale range per year		Standard	Titanium, 7000 m (23,000 ft)
Resolution			Weight in air: 4.2 kg (9.2 lbs)
Conductivity:	0.00001 S/m (0.0001 mS/cm)		Weight in water: 2.8 kg (6.2 lbs)
Temperature:	0.0001 °C	Optional ShallowCAT	Plastic, 250 m (820 ft)
Optional Pressure: 0.002% of full scale range			Weight in air: 3.1 kg (6.9 lbs)
	_		Weight in water: 1.7 kg (3.8 lbs)

\* Power consumption values are for standard RS-232 interface; for optional RS-485 interface, see RS-485 manual.





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