

ECO Volume Scattering Function Meter

(VSF)

User's Guide (all models)

The user's guide is an evolving document. If you find sections that are unclear, or missing information, please let us know. Check our website periodically for updates.

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ECO Sensor Warranty

This unit is guaranteed against defects in materials and workmanship for a period of one year after the original date of purchase. WET Labs will supply all replacement parts and labor and pay for return via 3rd day air shipping in honoring this warranty. This warranty is considered void if the factory determines that the unit was subjected to abuse or neglect beyond the normal wear and tear of field deployment, or in the event the pressure cans have been opened by the customer (this does not apply to pressure cans on battery-supplied units). The customer should call for a Return Manufacturer's Authorization (RMA) before returning the instrument to the factory and is responsible for shipping costs to WET Labs. WET Labs is not responsible for shipping damage done during the return shipment. WET Labs assumes no liability for equipment damage, personal injury or loss of data resulting from use of this instrument, except for that stated in this warranty.

Attention!

Return Policy for Instruments with Anti-fouling Treatment

WET Labs cannot accept instruments for servicing or repair that are treated with anti-fouling compound(s). This includes but is not limited to tri-butyl tin (TBT), marine anti-fouling paint, ablative coatings, etc.

Please ensure any anti-fouling treatment has been removed prior to returning instruments to WET Labs for service or repair.

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1. Specifications

Model	VSF(RT) ¹	VSF	VSFS	VSFB	VSFSB
Mechanical					
Diameter	2.48 in (6.3 cm)	2.48 in (6.3 cm)	2.48 in (6.3 cm)	2.48 in (6.3 cm)	2.48 in (6.3 cm)
Length	5.0 in (12.7 cm)	5.0 in (12.7 cm)	5.25 in (13.3 cm)	10.0 in (25.4 cm)	10.25 in (26.0 cm)
Weight, in air	0.9 lbs (0.4 kg)	0.9 lbs (0.4 kg)	1.1 lbs (0.5 kg)	2.1 lbs (0.96 kg)	2.1 lbs (0.96 kg)
Material	Acetron	Acetron	Acetron	Acetron	Acetron
Environmental					
Temperature range	0–30 deg C	0–30 deg C	0–30 deg C	0–30 deg C	0–30 deg C
Depth rating	600 m	600 m	300 m	300 m	300 m
Electrical					
Output resolution	12 bit	12 bit	12 bit	12 bit	12 bit
Internal data logging	N	Y	Y	Y	Y
Internal batteries	N	N	N	Y	Y
Connector	MCBH6M	MCBH6M	MCBH6M	MCBH6M	MCBH6M
Input	7–15 VDC	7–15 VDC	7–15 VDC	7–15 VDC	7–15 VDC
Current, typical	85 mA	85 mA	85 mA	85 mA	85 mA
Current, sleep	85 μ A	85 μ A	85 μ A	85 μ A	85 μ A
Data memory	--	1 MB (65,000 samples)	1 MB (65,000 samples)	1 MB (65,000 samples)	1 MB (65,000 samples)
Sample rate	to 10 Hz	to 10 Hz	to 10 Hz	to 10 Hz	to 10 Hz
RS-232 output	19200 baud	19200 baud	19200 baud	19200 baud	19200 baud
Anti-fouling bio-wiper™	N	N	Y	N	Y
Bio-wiper™ cycle	-	-	110 mA	-	110 mA
Optical					
Wavelength (nm)	470, 530, or 660	470, 530, or 660	470, 530, or 660	470, 530, or 660	470, 530, or 660
Sensitivity, min.	0.005 m ⁻¹ @ 1 Hz	0.005 m ⁻¹ @ 1 Hz	0.005 m ⁻¹ @ 1 Hz	0.005 m ⁻¹ @ 1 Hz	0.005 m ⁻¹ @ 1 Hz
Range, typical*	0–10 m ⁻¹ (b)	0–10 m ⁻¹ (b)	0–10 m ⁻¹ (b)	0–10 m ⁻¹ (b)	0–10 m ⁻¹ (b)
Linearity	99% R ²	99% R ²	99% R ²	99% R ²	99% R ²

VSF(RT)—Provides an RS-232 serial output with 4000-count range. This unit is programmably configurable for continuous operation.

VSF—Provides an RS-232 serial output with 4000-count range. This unit is programmably configurable for continuous operation or periodic sampling.

VSFS—Provides the capabilities of the VSF with an integrated anti-fouling *bio-wiper*™.

VSFB—Provides the capabilities of the VSF and self-recording with internal batteries for autonomous operation.

VSFSB—Provides the capabilities of the VSF with an integrated anti-fouling *bio-wiper*™ and self-recording with internal batteries for autonomous operation.

*Other ranges available upon request.

Specifications subject to change without notice.

1.1 Connectors

ECO VSF meters use a six-pin bulkhead connector. The pin functions for this connector are shown in Figure 1. Table 1 summarizes pin functions for the bulkhead connectors.

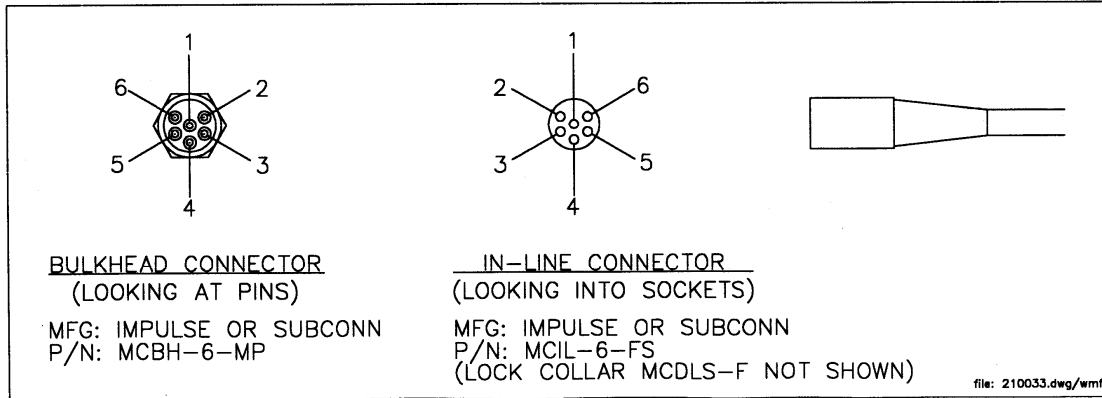


Figure 1. *ECO* VSF connector schematic

Table 1. Pinout summary for *ECO* connectors

Pin (or Socket)	Function
1	Ground
2	RS-232 (RX)
3	Reserved
4	V In
5	RS-232 (TX)
6	Configurable

WARNING

If you are going to build or use a non-WET Labs-built cable, do not use wires from pins 3 and 6 or the *ECO* meter will be damaged.

Input power of 7–15 volts DC is applied to pin 4. The power supply current returns through the common ground pin. The input power signal has a bi-directional filter. This prevents external power supply noise from entering into the *ECO* VSF, and also prevents internally generated noise from coupling out on to the external power supply wire. Data is sent out pin 5.

1.1.1 *ECO* VSFB and VSFSB Connectors

ECO VSFB and VSFSB (units with internal batteries) have an second bulkhead connector that comes with a jumper plug to supply power to the unit. The pin functions for this connector are shown in Figure 2. Table 2 summarizes pin functions for the 3-socket bulkhead connector.

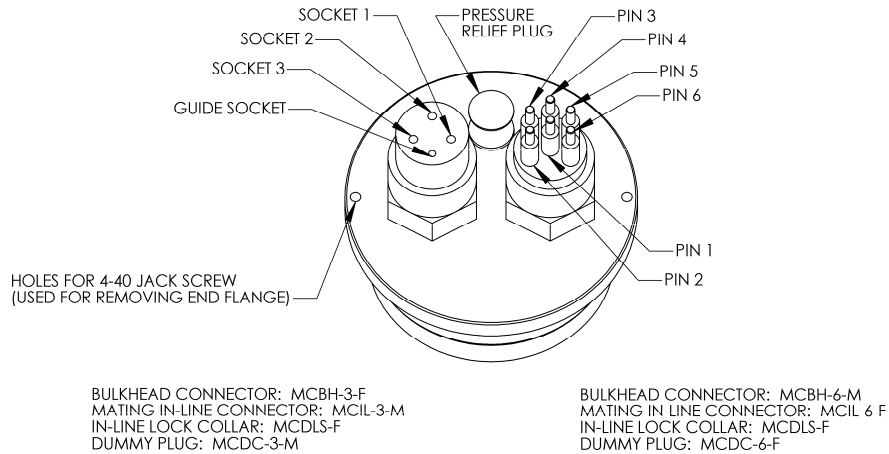


Figure 2. ECO VSFB and VSFSB connector schematic

Table 2. Pinout summary for *ECO* 3-socket connector

Pin (or Socket)	Function
1	V in
2	N/C
3	Battery out

1.2 Test Cable

A test cable is supplied with each unit. This cable includes three legs:

1. A power interface module provides power to the instrument from the connected 9 V battery.
2. A DB-9 serial interface connector.
3. A six-socket in-line connector plugs into the sensor to provide power and obtain signal.

1.3 Delivered Items

The standard VSF delivery consists of the following:

- the instrument itself
- test cable
- protective cover for optics
- dummy plug with lock collar
- this user's guide
- ECOView user's guide
- ECOView host program and device file (on CD)
- instrument-specific calibration sheet

- VSF(RT), VSF, VSFS: stainless steel mounting bracket and hardware (See Appendix A for details)
- one 0.050-in. hex key for *bio-wiper*TM removal (units with *bio-wiper*TM only)
- spare parts kit (battery units only):
 - Two end flange O-rings (size 224)
 - Two vent plug O-rings (size 010)
 - Two jacking screws for connector flange removal
 - One 3/32-in. hex key for jacking screws
 - Power plug for autonomous operation
 - Three pre-cut segments (7 inches) of 0.036-inch diameter monofilament for end flange
 - Three pre-cut segments (0.25 inches) of 0.094-inch diameter white nylon bar stock for replacing the white plastic dowel pin.

1.4 *Bio-wiper*TM

The VSFS and VSFSB have an integrated non-contact anti-fouling *bio-wiper*TM for use in extended deployments. This *bio-wiper*TM performs autonomously as part of a pre-programmed sampling sequence when a measurement is taken. The rate of closure and opening is dependent upon both temperature and depth.

1.5 Batteries

The VSFB and VSFSB incorporate six 9-volt batteries as their internal power source. They can either use standard alkaline cells for a total capacity of approximately 1000 mA-hrs, or for longer deployments can use LiMnO₂ cells to achieve more than 2000 mA-hrs of operational capacity. Actual total usage time of the internal batteries is a function of several parameters. These include nominal water temperature, sequence timing, sample periods, and total deployment duration.

For even greater deployment capability contact WET Labs for information on external battery packs.

2. Theory of Operation

The angular distribution of scattered radiation in the backward hemisphere is important in the interpretation of remote sensing measurements, investigations of particle shape, and models of visibility in seawater. The *ECO* VSF measures the optical scattering at 100, 125, and 150 degrees, thus providing the shape of the Volume Scattering Function (VSF) throughout its angular domain. Motivated by the need to better understand the relationship of water-leaving radiance with the backscattering into the same direction, the three-angle measurement allows determination of specific angles of backscattering through interpolation. Conversely, it also can provide the total backscattering coefficient by integration and extrapolation from 90 to 180 degrees.

Figure 3 shows the optical configuration for the VSF. The *ECO* VSF consists of a potted monolithic optical flange and a housing containing the signal processing and controller circuitry. The optics include three LED-based transmitters that couple to a single receiver. The transmitters and receiver are located to establish centroid light scattering angles of approximately 100, 125, and 150 degrees respectively. For each angle the region of intersection encompasses a FWHM bandwidth of about 18 degrees.

Figure 3. Optical configuration of *ECO*-VSF

The controller electronics sequence through the individual transmitters at approximately 1 Hz per sample cycle. The individual transmitters operate synchronously with the receiver to reject ambient light. A directly coupled reference detector indicates relative LED intensity during operation. Signals from the receiver and reference detector are digitized and subsequently stored or telemetered from the instrument.

The *ECO* VSF can be configured for a variety of applications. In addition to providing a continuous output, the instrument can internally record up to 65,000 samples of data. Additionally, for long-term deployments, the instrument can come equipped with an anti-fouling shutter to retard bio-fouling of the optical surfaces. Models with internal and external batteries are also available. Each sensor operates at one wavelength. Presently these wavelengths are factory configurable for 470 nm, 530 nm, and 660 nm.

3. Instrument Operation

Please note that certain aspects of instrument operation are configuration-dependent. These are noted where applicable within the manual. *ECO* sensors can be used in a moored or profiling mode, with or without a host computer/data logger. The *ECOs* are versatile instruments, capable of operating under a variety of user-selected settings

3.1 Initial Checkout

Supplied from the factory, *ECOs* are configured to begin continuously sampling upon power-on. Electrical checkout of *ECO* is straightforward.

Connect the 6-socket connector on the test cable to the instrument to provide power to the LEDs and electronics (see Section 1 for a diagram of the pinouts of *ECO VSF*). Connect the battery leads on the test cable to the 9V battery supplied with the meter. Light should emanate from the meter.

3.2 Operating the Sensor for Data Output

Note

ECO scattering meters are sensitive to AC light. Before making measurement, turn AC lighting off.

1. Connect the 6-socket connector to the instrument to provide power to the LEDs and electronics. Connect the DB-9 connector to a computer with the ECOView host program installed on it.

WARNING!

Always use a regulated power supply to provide power to ECO sensors if not using the 9V battery provided with the test cable: power spikes may damage the meter.

2. Start ECOView. Select the appropriate COM Port and Device File. Supply power to the meter, then click on the **Start Data** button. Output will appear in the Raw Data window. Place the flat of your hand in front of the sensor face and note that the signal will increase toward saturation (maximum value on calibration sheet) as your hand gets closer. When applying power to sensors with a *bio-wiper*TM, it will open and, depending on the settings, operate until you select **Stop Data** in ECOView (or input ! ! ! ! ! in a terminal program) The *bio-wiper*TM will close and the instrument will await the next command.
3. If the sensor completes the requested samples (this is common for meters set up in moored applications), it will go into sleep mode, and the meter will not light when power is cycled. To “wake” the meter, click **Stop Data** five times at the rate of two times per second immediately upon applying power. This interrupts the sensor, returning it to a “ready” state, awaiting commands.
4. Check the settings for the ECO and change if necessary. ECOView factory settings for continuous operation:
 - Set Number of Samples = 0
 - Set Number of Cycles = 0.
5. If the meter does not light after performing step 3, check the battery. Replace if necessary, perform steps 2 and 3 to verify communication. If it still does not light, contact WET Labs.

Refer to the ECOView User’s Guide for details about using the software.

3.3 Deployment

The *ECO* VSF meter requires no pump to assure successful operation. Once power is supplied, the unit is ready for submersion and subsequent measurements. Some consideration should be given to the package orientation. Do not face the sensor directly into the sun or other bright lights. For best output signal integrity, locate the instrument away from significant EMI sources.

Caution

The VSF should be mounted so that the LED source will not “see” any part of a cage or deployment hardware. This will affect the sensor’s output.

Other than these basic considerations, one only needs to make sure that the unit is securely mounted to whatever lowering frame is used and that the mounting brackets are not damaging the unit casing. The instrument can be used in a moored or profiling mode.

3.4 *Bio-wiper*TM Operation

The *ECO*-VSFS and -VSFSB are provided with an anti-fouling *bio-wiper*TM (Figure 4). The *bio-wiper*TM extends the possible deployment duration by retarding biological growth on the instrument’s optical surface. The *bio-wiper*TM covers the optical surface: 1) while the instrument is in “sleep” mode; 2) when it has completed the number of samples requested; and 3) when the user selects **Stop Data** in *ECOView* or types “!!!!” in a terminal program. When the meter wakes up, the optical surface is exposed by the *bio-wiper*TM counter-clockwise rotation.

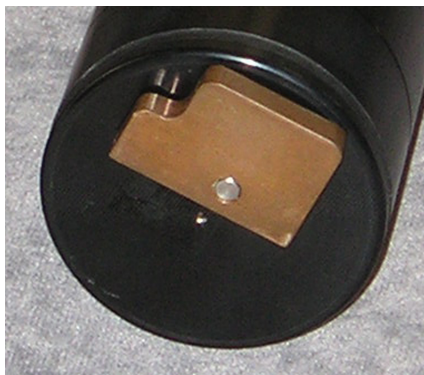


Figure 4. Anti-fouling *bio-wiper*TM

If power is shut off in mid cycle, the *bio-wiper*TM will reinitialize to the beginning of the user-selected settings when power is applied again.

3.4.1 *Bio-wiper*TM Cleaning and Maintenance

When not in active sample mode, the *bio-wiper*TM can be removed by using the factory-supplied 0.050 hex key to loosen the set screw that attaches the shutter to the instrument. Take care to ensure no unnecessary torque is placed on the shaft.

To clean, wash in soapy water, rinse and dry thoroughly. Note the condition of the copper on the instrument side of the shutter. It is normal for the copper *bio-wiper*TM to corrode and turn green, especially after the instrument has been removed from the water. This corrosion will slightly reduce the shutter's antifouling ability the next time it is deployed. For maximum antifouling capability:

1. Remove *bio-wiper*TM
2. Buff with a pad of green Scotch Brite[®] (or similar) until shiny
3. Re-install *bio-wiper*TM

When re-installing the *bio-wiper*TM on the instrument, the wiper blade must be properly flexed. To achieve the proper flex of the wiper, set the gap between the copper *bio-wiper*TM and the instrument face to 0.03 in. (0.8 mm). An improperly set gap will either fail to clean the face, or cause the motor to draw excessive current (Figure 5).

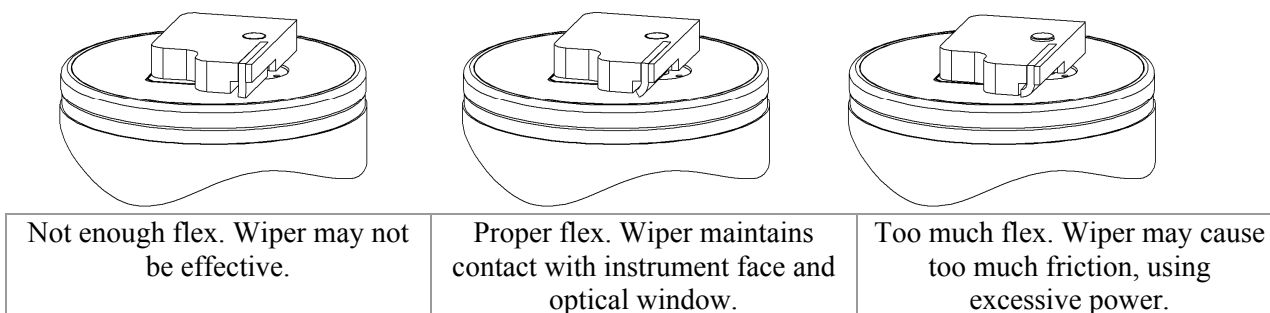


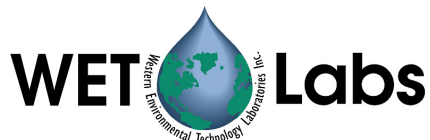
Figure 5. Adjusting *bio-wiper*TM for proper flex

To set this gap:

1. Fold a piece of paper in half, then in half again, then fold a third time, creasing the edges. It's now 8 sheets thick and about 0.03 in. thick.
2. Make sure the *bio-wiper*TM is in the closed position. You may have to run the instrument.
3. If it is not already loosened, loosen the set screw holding the *bio-wiper*TM and put the paper gage between the instrument face and the *bio-wiper*.
4. Push down on the *bio-wiper*TM and rotate it counter-clockwise so that the shutter is in the closed position.
5. Without letting the wiper spring up, tighten the set screw.
6. Run the instrument to verify operation

3.5 Upkeep and Maintenance

The *ECO* VSFs are compact devices and their maintenance can be easily overlooked. However, the VSF is a precision instrument and does require a minimum of routine upkeep. After each cast or exposure of the instrument to natural water, flush the instrument with clean



fresh water, paying careful attention to the sensor face. Use soapy water to cut any grease or oil accumulation. Gently wipe clean with a soft cloth and replace the protective cap on the optics face. The sensor face is composed of ABS plastic and optical epoxy and can easily be damaged or scratched.

WARNING

Do not use acetone or other solvents to clean the sensor.

At the end of an experiment, the instrument should be rinsed thoroughly, air-dried and stored in a cool, dry place.

4. VSFB and VSFSB: Using Internal Batteries

ECO meters with internal batteries can be powered in several ways.

1. The meter can be powered from the six-pin bulkhead connector using the test cable (set to ON BATT) or from an external source (test cable set to ON AUX). Communication is possible in this mode.
2. Alternatively, the meter can be powered using a jumper plug in the three-socket bulkhead connector. This is particularly useful for moored applications. The meter will run according to its stored settings.
3. If the jumper plug is in place on the meter and supplying power and the test cable is connected, power will be supplied by the equipment supplying the highest voltage. To conserve the internal batteries, it is advisable to use the test cable and an external power source set to 10–15 V.

4.1 Removing End Flange and Batteries

WARNING!

Changing the batteries will require opening the pressure housing of the *ECO* sensor. Only people qualified to service underwater oceanographic instrumentation should perform this procedure. If this procedure is performed improperly, it could result in catastrophic instrument failure due to flooding or in personal injury or death due to abnormal internal pressure as a result of flooding.

WET Labs Inc. disclaims all product liability from the use or servicing of this equipment. WET Labs Inc. has no way of controlling the use of this equipment or of choosing qualified personnel to operate it, and therefore cannot take steps to comply with laws pertaining to product liability, including laws that impose a duty to warn the user of any dangers involved with the operation and maintenance of this equipment. Therefore, acceptance of this equipment by the customer shall be conclusively deemed to include a covenant by the customer to defend and hold WET Labs Inc. harmless from all product liability claims arising from the use and servicing of this equipment. Flooded instruments will be covered by WET Labs Inc. warranties at the discretion of WET Labs, Inc.

1. Make sure the instrument is thoroughly dry.
2. Remove the dummy plugs.
3. With connector end flange pointed downwards away from face, release seal vent plug.
4. Remove moisture from vent plug area.
5. Using needle nose pliers, remove filament from end flange.
6. Lift flange from pressure housing until seal is broken. The jacking screws provided with sensor can be used to “push” the flange from the pressure housing and can then be removed or left in the end flange.
7. Remove excess moisture from flange–can seal area.
8. Work the end flange out of the pressure housing and remove any residual moisture. Remove the foam spacer and the neoprene insulator.

-
9. The battery pack is connected to the processor boards by a six-pin Molex connector: do NOT pull too hard or far on the battery pack or it will come unplugged and the unit will need to be returned to WET Labs.
 10. Gently pull the white cord at the loop to remove the battery pack from the pressure housing.
 11. Remove the black plastic protectors from the ends of the long screws securing the batteries.
 12. Loosen and remove the screws (3/16-in slotted driver).

4.2 Replacing End Flange and Batteries

1. Replace the batteries
2. Re-install the screws:
 - Align the groove in each of the plates so the six-wire extension bundle will fit in it along its length.
 - Be careful not to cross-thread into the bottom end plate nor to over-tighten the screws.
 - If they are too tight, the fiber washers that act as separators between the batteries will flex.
 - Make sure there are equal amounts of screw threads protruding from the bottom end plate when they are secure. This will ensure the pack is straight and will fit into the pressure housing with no difficulty.
1. Re-install the black plastic protective covers on the ends of the screws.
2. Remove and check the pressure housing O-ring for nicks or tears. Replace if necessary. Before re-installing, apply a light coat of vacuum grease on the O-ring.
3. Carefully replace the battery pack in the pressure housing. Place the neoprene insulator on the battery assembly and lay the white cord on the top.
4. Plug in the two-pin, then the six-pin Molex connectors. Sensor operation can now be tested if desired.
5. Align the hole in the end flange (NOT the jack screw holes) with the white dowel pin. While coiling the six wire bundle and making sure none are pinched between the end flange and the pressure housing, position the flange on the housing. Leave space to re-insert the gray foam spacer, making sure the cut-out accommodates the vent plug screw.
6. Push the end flange all the way on to the pressure housing, making sure no wires are pinched. Be sure the vent plug does not pop up. If it does, you'll need to re-position the foam spacer.
7. Re-insert the monofilament.

4.3 Checking Vent Plug, Changing O-Rings:

If there is fouling on the vent plug, it should be cleaned and the two 010 O-rings replaced. Otherwise, this mechanism should be maintenance-free.

WARNING!

The pressure housing is made of plastic material that scratches easily. Do not let the screwdriver slip and scratch the can when removing or replacing the vent plug. Use a toothpick (something softer than the plastic) to remove the O-rings from the vent plug.

1. Pull vent plug out about half way; hold plug while unscrewing the truss screw. When screw is removed, pull vent plug from end flange.
2. “Pinch” bottom O-ring around vent plug to form a small gap you can work a toothpick into. Use the toothpick to help roll the bottom O-ring off the plug.
3. Perform the same procedure with the top O-ring.
4. Clean the vent plug and vent plug hole using a dry lint-free tissue or cotton swab.
5. Lightly coat two undamaged or new O-rings with silicon grease. Install the top O-ring (nearest to large end of plug) first, then the bottom one.
6. Insert vent plug into its hole in the end flange and hold it while inserting the truss screw. Rotate the vent plug to begin tightening the screw. Finish tightening using a screwdriver, being careful not to overtighten truss screw.

Note

A portion of the truss screw head has been removed to allow for venting in case of pressure buildup.

5. Data Analysis

Data from the *ECO* VSF represents raw output from the sensor. Applying linear scaling constants, this data can be expressed in meaningful forms of inverse meters for each of the respective angles.

5.1 Data Corrections

Attenuation coupling—Many scattering sensors require a subsequent attenuation correction for pathlength coupling of the transmitted and scattered light. This is typically a function of the propagation distances of the light as well as the magnitude of the water attenuation. Because the *ECO* VSF incorporates very short pathlengths and scattering volumes in its measurements, it is relatively immune to this pathlength coupling (Figure 6). For attenuation coefficients up to approximately 4 m^{-1} no data correction is required. If you are operating the meter in waters with greater turbidity, contact the factory for configuration information.

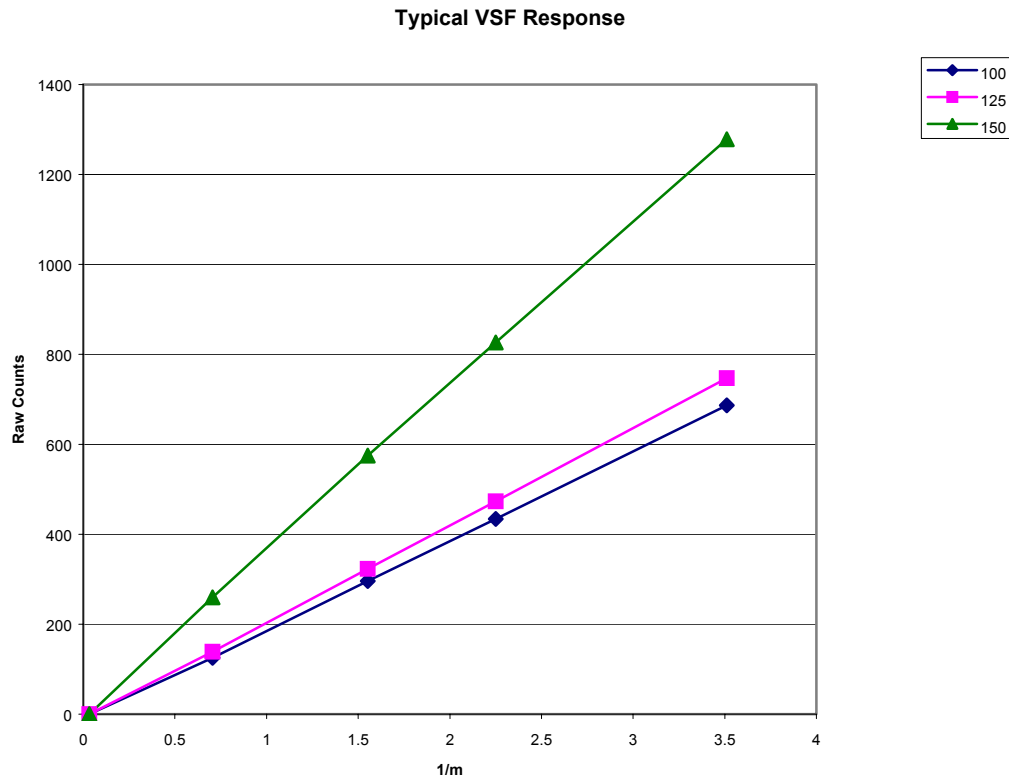


Figure 6. Linearity Response

Temperature correction—Output from an LED reference detector is provided, which gives an indication of relative LED intensity during operation.

Obtaining angular values in inverse meters—The primary angular values for each angle of backscattering are directly calculated by ECOView or alternatively can be applied upon raw data downloaded from the instruments. Determination is made by subtracting the clean water offset from the measured value and multiplying the result by the scaling factors provided in the calibration sheet.

The scaling coefficients for these values are determined by our instrument calibration process as described in Section 6.2.

5.2 Determining other Angle-Specific Coefficients

Other angular scattering coefficients can be determined through interpolation between the measured angles. At this time WET Labs offers no preference in the type of curve fit to use for deriving these coefficients.

5.2.1 Determining Backscattering Coefficient

The most accurate method of determining the backscattering coefficient, b_b , from the VSF measured at the three angles of the *ECO* VSF is as follows:

1. Multiply the corrected β values by $2\pi\sin\theta$ to convert to a polar steradian area.
2. Fit a 3rd order polynomial to the three measured points and a fourth value of π radians = 0 ($\sin(\pi \text{ radians}) = 0$).
3. Integrate under the curve fit from $\pi/2$ to π radians.
4. Add 1.3 percent to the backscattering estimate.

Testing this approach with all the Petzold (1972) VSFs results in a maximum error of about 1 percent.

(Petzold, T.J., 1972. *Volume scattering functions for selected natural waters*. Scripps Institution of Oceanography, Visibility Laboratory, San Diego, CA, SIO Ref. 71–78.)

6. Testing and Calibration

Prior to shipment, each *ECO* is characterized to ensure that it meets the instrument's specifications.

6.1 Testing

When the instrument is completely assembled, it goes through the tests below to ensure performance.

6.1.1 Pure Water Blank

Pure, de-ionized water is used to set the “zero” voltage of the meter. This zero voltage is set for 150 counts (+/-50) on all models.

6.1.2 Pressure

To ensure the integrity of the housing and seals, *ECOs* are subjected to a wet hyperbaric test before final testing. The testing chamber applies a water pressure of at least 50 PSI.

6.1.3 Mechanical Stability

Before final testing, the *ECO* meters are subjected to a mechanical stability test. This involves subjecting the unit to mild vibration and shock. Instrument functionality is verified afterwards.

6.1.4 Electronic Stability

This value is computed by collecting a sample once every 5 seconds for twelve hours or more. After the data is collected, the standard deviation of this set is calculated and divided by the number of hours the test ran. The stability value must be less than 3 counts.

6.1.5 Noise

The noise value is computed from a standard deviation over 60 samples. These samples are collected at one-second intervals for one minute. A standard deviation is then performed on the 60 samples, and the result is the published noise on the calibration form. The calculated noise must be below 3 counts.

6.1.6 Voltage and Current Range Verification

To verify that the *ECO* operates over the entire specified voltage range (7–15 V), a voltage-sweep test is performed. *ECO* is operated over the entire voltage range, and the current and operation is observed. The total power consumption (voltage times current) must remain below 600 mW over the entire voltage range.

6.2 Calibration

Calibration of the *ECO* VSF involves the following steps.

1. Numerical determination of the volume weighted angular region for each scattering angle.

Figure 7. General geometry of the sensor

The detector (D) and the source (S) are separated by a distance SD .

The angle of the center of the detector beam with the line SD is θ_δ .

The half-angle of the detector cone is σ_δ .

The corresponding angles for the source are θ_σ and σ_σ .

The volume above the SD line is broken up into the small volumes $\Delta x \Delta y \Delta z$. z is in the same plane as the SD line.

The small volume, $\Delta V = \Delta x \Delta y \Delta z$ at (x, y, z) was determined by simple geometry. It was then determined whether the ΔV was in the intersection of the source beam and the field of view of the detector (both conical shapes). The intersection of each cone and the plane is an ellipse and the illuminated area is the intersection of those ellipses. The signal strength was determined for each elementary volume, and then integrated over the illuminated area to obtain the weighting function. Weighting functions were determined in this manner for each source–detector pair (nominal angles of 100, 125, and 150 degrees) and are plotted in the figure below.

Figure 8. Weighting functions for source–detector pairs

2. Mie scattering determination into these regions for a known distribution of spherical scatterers (Polystyrene beads).

Spherical or spheroid particles with a known particle size distribution can be quite accurately modeled for scattering behavior using Mie theory. We thus obtain NIST-traceable bead standards and calculate their scattering response using the derived weighting functions.

3. Determination of angular coefficients through direct measurement of spherical beads.

Once the weighting functions are determined and the scattering response for our calibration medium determined, we then run a dilution series of measurements, using the medium in water. From the curves obtained with varying concentration we then calculate the absolute response of the instrument. These are the scaling coefficients supplied with each instrument.

7. General Terminal Communications

While WET Labs supplies a host software package for instrument configuration and data retrieval, the unit sensors can be controlled from a terminal emulator or customer-supplied interface software. This section outlines hardware requirements and low-level interface commands for this type of operations.

7.1 Communication Settings

baud rate: 19200
 data bits: 8
 parity: none
 stop bits: 1
 flow control: none

7.2 ECO Command List and Data Format

Command	Parameters passed	Description
!!!!	none	Stops data collection; allows user to input setup parameters. Note that if the meter is in a sleep state, the power must be turned off for a minute, then powered on while the “!” key is held down for several seconds. If this does not “wake” the meter, refer to the ECOView user’s guide Operation Tip to “wake” a meter in a low power sleep state to enable inputting setup parameters.
\$save	single number, 1 to 65535	Number of measurements for each reported value
\$clk	24hr format time, hhmmss	Sets the time in the Real Time Clock
\$dat	date, format ddmmyy	Sets the date in the Real Time Clock
\$emc	none	Erases the Atmel memory chip, displays menu when done
\$get	none	Reads data out of Atmel memory chip. Prints "etx" when completed.
\$int	24hr format time, hhmmss	Time interval between packets in a set
\$mnu	none	Prints the menu, including time and date
\$pkt	single number, 0 to 65535	Number of individual measurements in each packet
\$rec	1 (on) or 0 (off)	Enables or disables recording data to Atmel memory chip
\$rls	none	Reloads settings from flash
\$run	none	Executes the current settings
\$set	single number, 0 to 65535	Number of packets in a set
\$sto	none	Stores current settings to internal flash

8. Device and Output Files

The ECOView host program requires a device file to provide engineering unit outputs for any of its measurements. Except for the first line in the device file, all lines of information in the device file that do not conform to one of the descriptor headers will be ignored. Every ECOView device file has three required elements.

8.1 Plot Header

The first line in the device file is used as the plot header for the ECOView plots.

8.2 Column Count Specification

The Column Count Specification identifies how many columns of data to expect. It follows the format “Column=n.” The Column Count Specification must be present before any of the Column Descriptions are listed.

8.3 Column Description

Every column in the ECO meter’s output must have a corresponding Column Description in the device file. The following notation is used in identifying the elements of each Column Description.

x = the column number, starting with 1 as the 1st column

sc = scale

dc = dark count: meter output in air with optics head taped

off = clean water offset, meter output in clean water

mw = measurement wavelength—wavelength used by the sensor for its measurement

dw = display wavelength—display wavelength—wavelength/color range (380–780 nm)

v = measured volts dc (not used on VSF)

Valid Column Descriptions are listed below.

Date=x	MM/DD/YY
Time=x	HH:MM:SS
REF=x	Reference Counts—Currently not used by ECOView
N/U=x	The column is Not Used

8.4 Sample Device File

Below is the standard device file for a VSF at 530 nm.

```
ECO VSF-059g
Created on: 10/30/03
```

```
Columns=7
Date=1
Time=2
ref=3
vsf100=4          1.36E-03          73
vsf125=5          1.46E-03          86
vsf150=6          1.39E-03          103
N/U=7
```

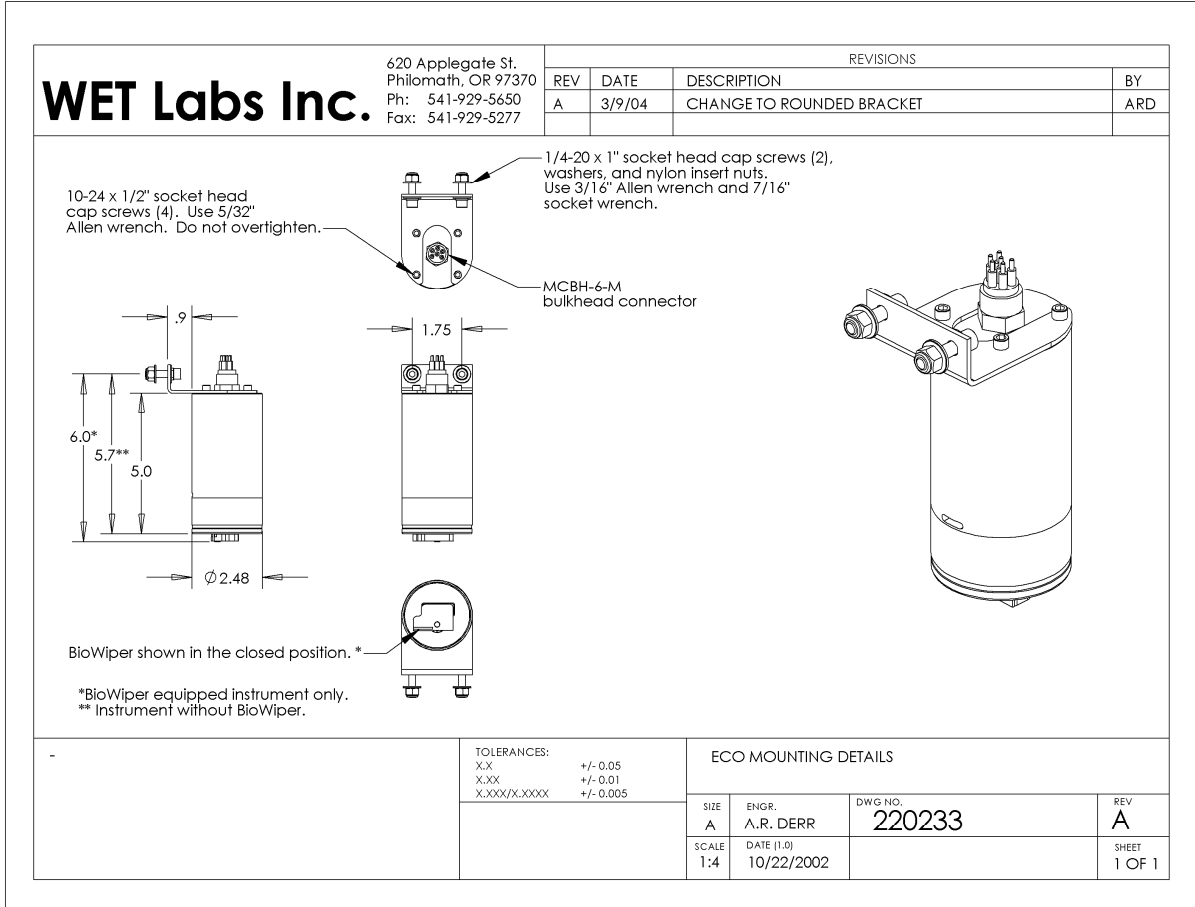
8.5 Sample Output File

Below is a sample output file for a VSF. From left to right, columns describe:

1. Date (MM/DD/YY)
2. Time (HH:MM:SS)
3. Reference
4. 100 degree angle output signal
5. 125 degree angle output signal
6. 150 degree angle output signal
7. Thermistor

```
9/17/2003  13:11:20  1745  165  173  400  543
9/17/2003  13:11:21  1743  168  176  396  543
9/17/2003  13:11:22  1742  162  176  396  542
9/17/2003  13:11:23  1742  167  177  394  542
9/17/2003  13:11:24  1741  163  174  392  542
9/17/2003  13:11:25  1741  167  174  396  542
9/17/2003  13:11:26  1741  163  180  398  542
9/17/2003  13:11:27  1740  168  176  390  542
9/17/2003  13:11:28  1740  166  174  393  542
9/17/2003  13:11:29  1740  164  174  393  542
9/17/2003  13:11:30  1740  166  174  394  542
9/17/2003  13:11:31  1740  165  176  395  541
```

Appendix A: Mounting Bracket Drawing



Revision History

Revision	Date	Revision Description	Originator
A	04/06/00	New document (DCR 22)	C. Carlock, C. Moore, W. Strubhar
B	09/20/00	Add vent plug maintenance steps (DCR 55)	D. Whiteman
C	09/25/00	Add explanation of ECO Host date format (DCR 56)	C. Carlock
D	10/18/00	Add lithium battery warning (DCR 65)	H. Van Zee
E	10/31/00	Add ECO Host 4, Shuttered specs, jumper plug note (DCR 68)	C. Carlock, H. Van Zee
F	11/13/00	Add aux. output explanation (DCR 72)	W. Strubhar
G	01/18/01	Correct setup and testing procedure, explanation of Interrupt Autostart on shuttered units (DCR 78)	C. Carlock
H	07/12/01	Update to ECO Host v. 4.1.2 (DCR 130)	C. Carlock
I	09/18/01	Add spare monofilament and plastic bar stock to shipping list (DCR 146)	H. Van Zee
J	11/5/01	Change LED wavelength values (DCR 159)	H. Van Zee
K	11/15/01	Add references to device file (DCR 161)	D. Whiteman
L	01/16/02	Update reference to test cable (DCR 185)	M. Avery
M	03/13/02	Correct VSFS/VSFB weights (DCR 201)	H. Van Zee
N	04/10/02	Update Section 3 (DCR 204)	D. Whiteman
O	04/16/02	Add max. samples to specifications (DCR 215)	D. Whiteman
P	07/08/02	Add internal battery option to spec. table (DCR 228)	H. Van Zee
Q	07/25/02	Delete inaccurate references to shutter specifications (DCR 238)	H. Van Zee
R	2/10/03	Delete lithium battery warning (DCR 272)	D. Whiteman
S	2/24/03	Change "shutter" to "bio-wiper™" (DCR 280)	H. Van Zee
T	4/14/03	Add stop command to terminal communications (DCR 292)	W. Strubhar
T1	10/30/03	Delete references to ECO Host, update to round board specs (draft)	H. Van Zee
U	11/24/03	Delete references to ECO Host, update to round board specs (DCR 344)	D. Romanko, H. Van Zee, D. Whiteman
V	11/25/03	Update Specifications (DCR 338)	I. Walsh
W	2/17/04	Update bio-wiper maintenance and column description for device files (DCR 367)	A. Derr, I. Walsh
X	3/10/04	Add new test cable description, operational description, mounting diagram (DCR 381)	A. Derr, D. Whiteman